

SYSTEM AND METHOD FOR  
MULTI-SYMBOL INTERFACING

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TECHNICAL FIELD OF THE INVENTION

The present invention relates generally to the  
15 field of interfacing, and more particularly, to a  
system and method for multi-symbol interfacing.

CROSS-REFERENCE TO RELATED PATENT APPLICATION

This application relates to the subject matter  
20 disclosed in the following co-pending United States  
Applications:

United States Patent Application Serial No.  
09/135,986 filed on August 17, 1998, entitled "Advanced  
Input/Output Interface For Integrated Circuit Device;"

25 United States Patent Application Serial No.  
09/369,636 filed on August 6, 1999, entitled  
"Input/Output Interfacing For A Semiconductor Chip;"  
and

United States Patent Application Serial No.  
30 09/452,274 filed on November 30, 1999, entitled  
"Universal Synchronization Clock And Skew Correction In  
A Bus System."

The above co-pending applications are assigned to the present Assignee and are incorporated herein by reference.

5 BACKGROUND OF THE INVENTION

In the electronic arts, data and information is routinely communicated or transferred between various devices, such as, for example, two computers, two integrated circuit (IC) devices, two conductive nodes,  
10 etc. Typically, such data/information is conveyed via one or more electrical signals carried over a suitable channel. Exemplary channels include copper wire, printed circuit board (PCB) trace, metallization line, and the like. As electronics have improved, there has  
15 been a corresponding need to transfer data/information at ever higher rates. High-speed transfer, however, has been hindered by a number of factors including, for example, limitations of the signaling technology used to transfer data/information over carrier channels and  
20 also the bandwidth of the channels themselves.

SUMMARY OF THE INVENTION

The present invention provides a system and method which implement a multi-symbol signaling technique for  
25 the transfer of data and information from an originating element to a destination element, each of which can be some electrical device (e.g., computer, IC device, node, etc.). In this technique, a number of symbols are used to transfer or convey bits of  
30 data/information in a signal. In one embodiment, each symbol transfers multiple bits of data/information. Each symbol may be defined by some unique combination

of a particular transition of the carrier signal and a particular signal region. A transition can be, for example, a rise from a lower signal level to a higher signal level (a rising transition) or, alternatively, a drop from a higher signal level to a lower signal level (a falling transition). A region can be, for example, any signal level above a predetermined voltage (an upper region) or, alternatively, any signal level below a predetermined voltage (a lower region).

10       The originating element outputs a transmission signal with the symbols. When the transmission signal is received by the destination element, it is sampled multiple times (i.e., "multi-sampled") for each symbol. This obtains at least a first and a second sampled values. The first and second sampled values are compared against each other to determine the defining transition of the symbol. For example, assuming that the first sample is taken before the second sample, if the first sampled value is greater than the second sampled value, then the transition is falling. On the other hand, if the first sampled value is less than the second sampled value, then the transition is rising. In addition, the two sampled values are averaged and further processed to create a "Q+avg" and a "Q-avg," which may serve as "predetermined" voltages. Q+avg and a Q-avg are then considered against each other. If the value of Q+avg is greater than the value of Q-avg, then the symbol lies within the upper region. If the value of Q+avg is less than the value of Q-avg, then the symbol lies within the lower region. Once the transition and region for the symbol are determined,

the symbol can be identified and then interpreted to recover the corresponding data/information.

According to an embodiment of the present invention, an apparatus for providing multi-symbol signaling includes a multi-symbol encoder circuit. The multi-symbol encoder circuit is operable to encode data into a plurality of symbols, each symbol uniquely defined by a signal transition and a signal region in a carrier signal. A driver circuit, coupled to the multi-symbol encoder circuit, is operable to drive the carrier signal.

According to another embodiment of the present invention, an apparatus is provided for recovering data from multi-symbol signaling. The apparatus includes a pre-amplifier which is operable to receive a carrier signal conveying a plurality of symbols. Each symbol is uniquely defined by a signal transition and a signal region in the carrier signal; each symbol represents a plurality of data. A region detector and a transition detector are coupled to the pre-amplifier. The region detector is operable to determine the defining signal region for each symbol. The transition detector is operable to determine the defining signal transition for each symbol.

According to yet another embodiment of the present invention, a method for providing multi-symbol signaling includes: receiving data for output from an originating device; encoding the data into a plurality of symbols, each symbol uniquely defined by a signal transition and a signal region in a carrier signal; and transmitting the carrier signal out of the originating device to a destination device.

According to still another embodiment of the present invention, a method for recovering data from multi-symbol signaling includes: receiving a carrier signal conveying a plurality of symbols, each symbol uniquely defined by a signal transition and a signal region in the carrier signal, each symbol representing a plurality of data; determining the defining signal region for each symbol; and determining the defining signal transition for each symbol.

10 According to still yet another embodiment of the present invention, a system is provided for multi-symbol signaling between monolithic semiconductor devices. The system includes a transmitter circuit and a receiver circuit. The transmitter circuit is  
15 integral to a first monolithic semiconductor device. The transmitter circuit is operable to encode a sequence of data into a plurality of symbols, each symbol uniquely defined by a signal transition and a signal region. The transmitter circuit is operable to  
20 output a transmission signal conveying the plurality of symbols. The receiver circuit is integral to a second monolithic semiconductor device. The receiver circuit is operable to receive the transmission signal conveying the plurality of symbols and to recover the  
25 sequence of data by detecting the signal transition and the signal region for each symbol.

A technical advantage of the present invention includes providing a transition of signal level in each symbol used to transfer data. The DC level of a  
30 channel may drift due to line characteristics when the same signal level appears on the channel over multiple clock cycles. In particular, capacitive and inductive

characteristics of a line may cause the DC level to rise or fall over time. Because the present invention provides a transition in each symbol, the signal level in the channel changes with each clock cycle, and thus, 5 capacitive and inductive charging on the line is minimized or attenuated with the present invention.

Another technical advantage of the present invention includes encoding data using symbols which can be interpreted without reference to absolute 10 values. This is accomplished by defining symbols with signal transitions and signal regions. To recover at least a portion of the data, two samples of signal level are taken for each symbol. For each sample, two differentials are generated. The differentials are 15 compared against each other. The relative positioning (i.e., higher or lower) of the differentials is considered in determining how to decode data. To recover another portion of data, each set of differentials is averaged. The averages are then 20 considered against each other in determining how to decode the data. Because the decoding of symbols is not accomplished using absolute reference levels, this multi-symbol signaling technique is not as susceptible as previously developed techniques to the problems 25 associated with signal drift and individual line characteristics. Accordingly, the present invention provides for accurate data recovery.

Yet another technical advantage of the present invention includes providing a signaling technique 30 which uses a predetermined voltage (e.g., a termination voltage ( $V_{TT}$ )) as a reference. This eliminates the need for a separate reference voltage source ( $V_{REF}$ ).

Accordingly, the signaling technique requires less power. Furthermore, the signaling technique provides more stable DC levels, thus enabling faster data transfer rates.

5 Other important technical advantages of the present invention are readily apparent to one skilled in the art from the following figures, descriptions, and claims.

10 BRIEF DESCRIPTION OF THE DRAWINGS

For a more complete understanding of the present invention and for further features and advantages, reference is now made to the following description, taken in conjunction with the accompanying drawings, in  
15 which:

Figure 1 illustrates an exemplary architecture in which a multi-symbol signaling technique, in accordance with an embodiment of the present invention, can be used;

20 Figure 2 illustrates an exemplary embodiment for a multi-symbol signaling scheme, in accordance with an embodiment of the present invention;

Figure 3 is a block diagram of a master device having circuitry for implementing the multi-symbol  
25 signaling technique, in accordance with an embodiment of the present invention;

Figure 4 is a block diagram of a slave device having circuitry for implementing the multi-symbol  
30 signaling technique, in accordance with an embodiment of the present invention;

Figure 5 is a block diagram of a multi-symbol transceiver, in accordance with an embodiment of the present invention;

Figure 6A is a block diagram of one embodiment for  
5 a multi-symbol transmitter and a corresponding truth table, in accordance with an embodiment of the present invention;

Figure 6B is a block diagram of another embodiment for a multi-symbol transmitter and a corresponding  
10 truth table, in accordance with an embodiment of the present invention;

Figure 6C illustrates output waveforms for the embodiment of multi-symbol transmitter of Figure 6B;

Figure 7 is a logic diagram of a multi-symbol  
15 encoder and a corresponding truth table, in accordance with an embodiment of the present invention;

Figure 8 is a timing diagram corresponding to the multi-symbol encoder of Figure 7;

Figure 9 is a block diagram of a multi-symbol  
20 correlated multi-sampling (CMS) receiver, in accordance with an embodiment of the present invention;

Figure 10 is a schematic diagram of a pre-amplifier and corresponding illustrations of input and output waveforms, in accordance with an embodiment of  
25 the present invention;

Figures 11A-11D are input waveforms showing transition and region for each of a plurality of symbols for transition detection;

Figure 11E is a schematic diagram of a  
30 differencing circuit for use in the transition detector of Figure 9, in accordance with an embodiment of the present invention;



Figure 11F is a schematic diagram of a differential latch amplifier with a pre-charge circuit for use in the transition detector of Figure 9, in accordance with an embodiment of the present invention;

5        Figure 11G is a schematic diagram of a hold circuit for use in the transition detector of Figure 9, in accordance with an embodiment of the present invention;

10        Figures 12A-12D are input waveforms showing transition and region for each of a plurality of symbols for region detection;

Figure 12E is a schematic diagram of an averaging circuit for use in the region detector of Figure 9, in accordance with an embodiment of the present invention;

15        Figure 12F is a schematic diagram of a differential latch amplifier with a pre-charge circuit for use in the region detector of Figure 9, in accordance with an embodiment of the invention;

20        Figure 12G is a schematic diagram of a hold circuit for use in the region detector of Figure 9, in accordance with an embodiment of the present invention;

25        Figure 13 is a schematic diagram of a pre-charge circuit for use with the differential latch amplifiers of Figures 11F and 12F, in accordance with an embodiment of the present invention; and

Figure 14 is a timing diagram for multi-symbol data transfer control, in accordance with an embodiment of the present invention.

### 30    DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

The preferred embodiments of the present invention and their advantages are best understood by referring

to Figures 1 through 14 of the drawings. In these drawings, like numerals are used for like and corresponding parts.

## 5 Architecture

Figure 1 illustrates an exemplary architecture 10 in which a multi-symbol signaling technique, according to an embodiment of the present invention, can be used. As depicted, architecture 10 includes a master device 12 and one or more slave devices 14. Master device 12 and slave devices 14 are electronic devices connected in a master/slave distributed system. Master device 12 controls this distributed system. Master device 12 can communicate with each of slave devices 14, and also with other master devices (not shown). Each of slave devices 14 can only communicate with master device 12. Each of master device 12 and slave devices 14 can be any suitable electronic device, such as, for example, a computer, an integrated circuit (IC) device, a conductive node, etc.

To provide a context for the present invention, the remainder of this description will primarily describe master device 12 and slave devices 14 as IC devices. In particular, master device 12 may be described as a processing device, and slave devices 14 may be described as memory devices. As a processing device, master device 12 generally functions to process data and other information, which may be transferred to and from other devices for control, addressing, and other operations. A processing device may comprise a microcontroller, a microprocessor, a central processing unit (CPU), a co-processor, a peripheral controller, a

graphic controller (two-dimensional or three-dimensional), a mass storage controller, or other semiconductor chip for processing data and information. As a memory device, each slave device 14 generally functions to store the data and other information. For this purpose, each slave device 14 can be any suitable IC memory including dynamic random access memory (DRAM), static random access memory (SRAM), non-volatile random access memory (NVRAM), and read only memory (ROM), such as erasable programmable ROM (EPROM), electrically erasable programmable ROM (EEPROM), and flash memory. Master device 12 and slave devices 14 can each be implemented as a separate monolithic, semiconductor device. Master device 12 and slave devices 14 can each be separately packaged in suitable packaging (e.g., plastic, ceramic, micro-ball grid array (MBGA), or chip scale package (CSP)) with suitable leads or other connecting points extending therefrom (not shown). Alternatively, master device 12 and slave devices 14 can be combined within a single package. It should be understood, however, that the present invention is not limited to this particular context, but has broader applicability. For example, master device 12 and slave devices 14, acting as originating and destination elements, can be formed on a single monolithic, semiconductor device.

Data and information may be transferred or communicated between master device 12 and slave devices 14. For any given transfer of data/information, the device originating the data/information is considered to be the originating element, and the device for which

the data/information is destined is considered to be the destination element.

The transfer of data/information may occur through one or more suitable channels. In this context, the channels may be implemented in a symbol bus 16 (for data) and a symbol bus 18 (for address and control information). These buses connect master device 12 and slave devices 14. As used herein, the terms "connected," "coupled," or any variant thereof, mean any connection or coupling, either direct or indirect, between two or more elements; the connection or coupling can be logical or physical. Symbol bus 16 (for data) may have a bus width of  $m$  bits. Symbol bus 18 (for address and control information) may have a bus width of  $a+b$  bits.

Symbol buses 16 and 18 may each comprise one or more traces on a printed circuit board (PCB). Each of the buses 16 and 18 may implement a suitable connection between electronic devices. Such connection can be, for example, a specialized connection (e.g., MX-ARC DDR) or an industry standard bus connection (e.g., a PC-100, PC-133, PC-200, or PC-266 DDR). Symbol buses 16 and 18 are each provided with a termination resistor ( $R_t$ ) connected to a termination voltage source ( $V_{TT}$ ). The termination resistors serve as a pull-up resistors to match bus impedance, thus minimizing signal reflection on the respective buses. The termination voltage source ( $V_{TT}$ ) may serve as a predetermined voltage, which can be used as a reference.

Numerous signals (generated within or received by any of master device 12 or slave devices 14) convey, or control or coordinate the conveyance of,

data/information to and from the devices via buses 16 and 18. In the present context, these signals include data signals for conveying data, addressing signals for identifying specific memory cells into and from which data is to be written or read, and control signals for coordinating or controlling the access, reading, and/or writing of the data.

According to an embodiment of the present invention, a multi-symbol signaling technique can be used for the signaling. In this technique, a number of symbols are used to transfer or convey bits of data/information in a signal from one electronic device to another. Each symbol may be uniquely defined or characterized by a particular combination of signal region and transition in signal value. A region can be, for example, a region above a predetermined voltage (e.g., a termination voltage ( $V_{TT}$ ) of the carrier channel) or, alternatively, a region below the predetermined voltage. A transition can be, for example, a rise from a lower signal level to a higher signal level (a positive slope), or alternatively, a drop from a higher signal level to a lower signal level (a negative slope). Each symbol may transfer multiple bits of data/information in a single clock (CLK) cycle.

To determine the defining transition of a symbol, at least two samples of signal value may be taken from the carrier signal (i.e., "multi-sampling"). The two sampled signal values are then compared. If the first sampled signal value is lower than the second sampled signal value, there is a rising transition in the symbol. Alternatively, if the first sampled signal value is higher than the second sampled signal value,

there is a falling transition in the symbol. In addition, to determine the defining region of a symbol, the two sampled signal values are averaged and then considered against the value of the predetermined  
5 voltage. If the average value of the two samples is greater than the predetermined voltage value, then the symbol lies within the upper region. If the average value of the two samples is less than the predetermined voltage value, then the symbol lies within the lower  
10 region. Once the transition and region for the symbol are determined, the symbol can be identified and then interpreted to recover the corresponding data/information.

A technical advantage of the present invention  
15 includes encoding data using a symbols which can be interpreted without reference to absolute values. This is accomplished by defining symbols with signal transitions and signal regions. To recover at least a portion of the data, two samples of signal level are  
20 taken for each symbol. For each sample, two differentials are generated. The differentials are compared against each other. The relative positioning (i.e., higher or lower) of the differentials is considered in determining how to decode data. To  
25 recover another portion of data, each set of differentials is averaged. The averages are then considered against each other in determining how to decode the data. Because the decoding of symbols is not accomplished using absolute reference levels, this  
30 multi-symbol signaling technique is not as susceptible as previously developed techniques to the problems associated with signal drift and individual line

characteristics. Accordingly, the present invention provides for accurate data recovery.

To implement the multi-symbol signaling technique in architecture 10, master device 12 and slave devices 5 14 each comprise a multi-symbol transceiver 34 connected to Symbol bus 16 for conveying data signals. Furthermore, master device 12 may include a multi-symbol transmitter 44 and slave devices 14 may each comprise a multi-symbol receiver 48 for transmitting and receiving control and address information signals. 10 In one embodiment, each multi-symbol transceiver 34 may comprise a multi-symbol transmitter 44 and a multi-symbol receiver 48. Multi-symbol transceivers 34, multi-symbol transmitter 44, and multi-symbol receivers 15 48 are described below in more detail.

#### Multi-Symbol Signaling Scheme

Figure 2 illustrates an exemplary embodiment for a multi-symbol signaling scheme 30, according to an embodiment of the present invention. Multi-symbol 20 signaling scheme 30 can be used to transfer data and information between an originating element and a destination element.

The multi-symbol signaling scheme 30 comprises a 25 plurality of symbols 32, which are separately referred to by reference numerals 32A, 32B, 32C, and 32D. These symbols 32 are separately designated "symbol-00," "symbol-01," "symbol-10," and "symbol-11." Each symbol 32 can be carried or appear as a waveform in a carrier 30 signal.

Each symbol 32 is uniquely defined by a transition of signal level and a signal region. As depicted,

three signal levels are available in the carrier signal. These levels, in increasing order, are as follows: voltage low (VL), bus termination voltage (VTT), and voltage high (VH). In one embodiment, the  
5 value of VL can be VTT minus  $\Delta V$ , and the value of VH can be VTT plus  $\Delta V$ , where  $\Delta V$  is selected so that there is sufficient signal-to-noise ratio to properly receive the carrier signal for a given channel (or bus).

A transition of signal level can be either rising  
10 from one signal level to another or falling from one signal level to another. Referring to the depicted symbols 32, symbol-00 and symbol-01 are each defined in part by a rising transition. In particular, in symbol-00, there is a rising transition from VL to VTT, and in  
15 symbol-01, there is a rising transition from VTT to VH. In like manner, symbol-10 and symbol-11 are each defined in part by a falling transition. In particular, in symbol-10, there is a falling transition from VTT to VL, and in symbol-11, there is a falling  
20 transition from VH to VTT.

A signal region may be generally characterized as a region above or below a particular demarcation signal level, or as a region between two demarcation signal levels. As depicted, an upper region may be defined as  
25 a region lying above a demarcation of the VTT signal level, or alternatively, as a region between the demarcations of the VTT and VH signal levels. A lower region may be defined as a region lying below the demarcation of the VTT signal level, or alternatively,  
30 as a region between the demarcations of the VTT and VL signal levels. Referring to the depicted symbols, symbol-00 and symbol-10 each lie within the lower



region (i.e., below  $V_{TT}$ , or between  $V_L$  and  $V_{TT}$ ).  
Symbol-01 and symbol-11 each lie within the upper  
region (i.e., above  $V_{TT}$ , or between  $V_{TT}$  and  $V_H$ ).

With the signal level transitions and signal  
5 regions described above, each symbol 32 may be uniquely  
defined by a particular combination of transition and  
region. That is, symbol-00 is uniquely defined by a  
rising transition and lying within the lower region.  
Symbol-01 is uniquely defined by a rising transition  
10 and lying within the upper region. Symbol-10 is  
uniquely defined by a falling transition and lying  
within the lower region. Symbol-11 is uniquely defined  
by a falling transition and lying within the upper  
region. This is reflected in a table 26.

15 Each symbol 32 may be transferred in a single  
clock (CLK) cycle. The defining transition of each  
symbol may occur approximately halfway through the  
clock cycle (and thus may coincide with a rising or  
falling edge of the clock signal). In order to  
20 identify a symbol, a first sample may be taken of a  
carrier signal during a first time period  $t_0$  (which can  
be the first half of a clock cycle) and a second sample  
may be taken of the carrier signal during a second time  
period  $t_1$  (which can be the second half of the same  
25 clock cycle).

Because the upper and lower regions can be  
characterized by the signal levels of  $V_L$ ,  $V_{TT}$ , and  $V_H$ ,  
each symbol 32 may be alternatively defined and  
identified by the respective signal levels occurring at  
30 the first and second halves of a clock signal. That  
is, symbol-00 is uniquely defined by a signal level  $V_L$   
at time period  $t_0$  and a signal level  $V_{TT}$  at time period

t1. Symbol-01 is uniquely defined by a signal level  $V_{TT}$  at time period  $t_0$  and a signal level  $V_H$  at time period  $t_1$ . Symbol-10 is uniquely defined by a signal level  $V_{TT}$  at time period  $t_0$  and a signal level  $V_L$  at time period  $t_1$ . Symbol-11 is uniquely defined by a signal level  $V_H$  at time period  $t_0$  and a signal level  $V_{TT}$  at time period  $t_1$ . This is reflected in a table 28.

Each symbol 32 may be used to transfer multiple bits of data/information. In the depicted embodiment, each symbol 32 transfers two bits of data/information. These bits may be referred to as "D0" and D1." Table 28 provides an exemplary encoding for the bits D0 and D1 as conveyed by symbol-00, symbol-01, symbol-10, and symbol-11. In particular, symbol-00 transfers a "low" or logic-0 value for each of D0 and D1. Symbol-01 transfers a "high" or logic-1 value for D0 and a "low" or logic-0 value for D1. Symbol-10 transfers a "low" or logic-0 value for D0 and a "high" or logic-1 value for D1. Symbol-11 transfers a "high" or logic-1 value for each of D0 and D1.

An advantage of the present invention includes defining a symbol in part by a *transition* of signal level, rather than an actual value for a signal level. If the actual values for signal levels drift together (e.g.,  $V_L$ ,  $V_{TT}$ , and  $V_H$  either all move up or all move down), then the transition in signal level is independent of the actual values. For example, even if the value of  $V_L$  rises by 0.5v, it will always be lower than  $V_{TT}$  if the value of  $V_{TT}$  rises in the same way (i.e., by 0.5v).

Furthermore, even if the actual values for signal levels do not drift together (e.g.,  $V_L$  may move up

while  $V_{TT}$  moves down), the transition in signal level can still be determined in all but the most severe cases. That is, the transition can be determined as long as the voltage difference between  $V_H$  and  $V_{TT}$ , and  
5 between  $V_{TT}$  and  $V_L$ , is greater than  $\Delta V$ .  $\Delta V$  is determined by the channel characteristics and the sensitivity of various elements of the multi-symbol transceiver 34 (as described herein). For most applications, as long as  $V_H$  is 100 mV higher than  $V_{TT}$ ,  
10 and  $V_{TT}$  is 100 mV higher than  $V_L$ , the symbols carrier signal can be read properly.

Thus, the multi-symbol signaling technique of the present invention provides highly robust capability to reject common-mode noise, as well as insensitivity to  
15 DC level drift in a carrier signal. Accordingly, the signaling technique supports reading of a signal with small margins at very high speed.

#### Master Device

20 Figure 3 is a block diagram of a master device 12 having circuitry for implementing the multi-symbol signaling technique, in accordance with an embodiment of the present invention. As shown, master device 12 is implemented as a processing device.

25 Master device 12 transfers data and other information to and from, for example, a slave device 14, for control, addressing, processing, and other operations. As depicted, master device 12 includes a memory controller 22 coupled to a processor 24.

30 Processor 24 functions to process data and other information, which may be transferred to and from the memory device for control, addressing, and other

operations. Memory controller 22 directs the transfer of data/information between processor 24 and the slave device.

Memory controller 22 includes a state machine 26,  
5 a delay locked loop (DLL) and control timing generator 31, *m*-number of multi-symbol transceivers 34, and a plurality of multi-symbol transmitters 44 (separately labeled 44A and 44B). State machine 26 generates all necessary interface control timings and addresses to  
10 perform one or more predetermined logical operations on data. These operations place state machine 26 in various states which control the input/output of data to and from master device 12.

DLL and control timing generator 31 receives an  
15 input system clock signal, which serves as symbol clock within master device 12. DLL and control timing generator 31 generates a number of clock, phase, and other signals. These signals include a clock (CLK) signal, an enable (ENB) signal, a phase Ø1 signal, a  
20 phase Ø2 signal, a phase Ø3 signal, a phase Ø4 signal, a phase ØEN1 signal, a phase ØEN2 signal, and a master clock CLKMaster signal. These signals are used in master device 12 for timing, synchronization, and other things.

25 For example, the clock (CLK) signal can be used for encoding data/information according to the multi-symbol signaling technique described herein. In one embodiment, the symbol clock runs at one-half the frequency of the clock (CLK) signal, thereby  
30 facilitating the design and implementation of DLL and control timing generator 31.

Each multi-symbol transceiver 34 and multi-symbol transmitter 44 is coupled to DLL and control timing generator 31 and receives the signals therefrom. Each multi-symbol transceiver 34 functions, among other things, to encode data being sent out of master device 12 into one or more symbols, drive outgoing signals, sample incoming signals, and reformat or recover data from the sampled incoming signals. Multi-symbol transceivers 34 transmit and receive signals on an  $m$ -bit Symbol bus. Each multi-symbol transmitter 44 functions to encode information being sent out of master device 12 into one or more symbols and drive outgoing signals. Multi-symbol transmitter 44A may be provided for address information and multi-symbol transmitter 44B may be provided for control information. Multi-symbol transmitters 44A, 44B transmit signals on a Symbol bus which may be  $a+b$  bits wide.

DLL and control timing generator 31, multi-symbol transceivers 34, and multi-symbol transmitters 44A, 44B of master device 12 cooperate to provide an interface for the input and output of data/information to and from master device 12. According to an embodiment of the present invention, DLL and control timing generator 31, multi-symbol transceivers 34, and multi-symbol transmitters 44A, 44B implement the multi-symbol signaling technique described herein.

#### Slave Device

Figure 4 is a block diagram of a slave device 14 having circuitry for implementing the multi-symbol signaling technique, in accordance with an embodiment

of the present invention. As shown, slave device 14 is implemented as a memory device. As depicted, slave device 14 includes DLL and control timing generator 31, *m*-number of multi-symbol transceivers 34, a plurality  
5 of multi-symbol receivers 48 (separately labeled 48A and 48B), and memory circuitry 36.

Memory circuitry 36 comprises a memory array 38. Memory array 38 includes a plurality of memory cells (not shown), each of which functions to maintain data.  
10 In particular, separate bits of data may be written into, stored, and read out of each of these memory cells. The memory cells may be fabricated in any suitable technology, such as metal-oxide semiconductor (MOS) technology, according to techniques well-known  
15 and understood by those skilled in the art of IC memory.

Further, these memory cells of memory array 38 can be organized in any suitable structure, such as, for example, a matrix of rows and columns. A typical  
20 architecture connects all cells in a row to a common row line, often referred to as a "word line," and all cells in a column to a common column line, often referred to as a "bit line." Any suitable addressing scheme, such as row-column (i.e., X-Y coordinate)  
25 addressing or content-addressing, can be used to access the memory cells within memory array 38.

Memory circuitry 36 also comprises address decoder circuitry 40 and other circuitry 42 which support the storage, maintenance, and/or access of information in  
30 the memory cells of memory array 38. For example, address decoder circuitry 40 may include a number of row address buffers, column address buffers, row

decoders, column decoders, and the like for accessing the various memory cells. Furthermore, circuitry 42 may include various timing generators, such as an output enable (OE) clock generator and a write enable  
5 (WE) clock generator, for enabling the reading and writing of data out of and into the memory cells. Circuitry 42 may also include circuitry for controlling and providing a data path for the transfer of data.

DLL and control timing generator 31 receives an  
10 input system clock signal, which serves a symbol clock within slave device 14. DLL and control timing generator 31 generates a number of clock, phase, and other signals. These signals include a clock (CLK) signal, an enable (ENB) signal, a phase Ø1 signal, a  
15 phase Ø2 signal, a phase Ø3 signal, a phase Ø4 signal, a phase ØEN1 signal, a phase ØEN2 signal, and a slave clock CLKSlave signal. These signals are used in slave device 14 for timing, synchronization, and other things.

20 As with master device 12, for example, the clock (CLK) signal can be used in slave device 14 for encoding data/information according to the multi-symbol signaling technique described herein. In one embodiment, the symbol clock runs at one-half the  
25 frequency of the clock (CLK) signal, thereby facilitating the design and implementation of DLL and control timing generator 31.

Each multi-symbol transceiver 34 and multi-symbol receiver 48 is coupled to DLL and control timing  
30 generator 31 and receives the signals therefrom. Each multi-symbol transceiver 34 functions, among other things, to encode data being sent out of slave device

14 into one or more symbols, drive outgoing signals, sample incoming signals, and reformat or recover data from the sampled incoming signals. Multi-symbol transceivers 34 transmit and receive signals on an  $m$ -bit Symbol bus. Each multi-symbol receiver 48 functions to receive incoming signals and recover information from one or more symbols contained therein. Multi-symbol receiver 48A may be provided for address information and multi-symbol receiver 48B may be provided for control information. Multi-symbol receivers 48A, 48B receive signals from a Symbol bus which may be  $a+b$  bits wide.

DLL and control timing generator 31, multi-symbol transceivers 34, and multi-symbol receivers 48A, 48B of slave device 14 cooperate to provide an interface for the input and output of data/information to and from slave device 14. According to an embodiment of the present invention, DLL and control timing generator 31, multi-symbol transceivers 34, and multi-symbol receivers 48A, 48B implement the multi-symbol signaling technique described herein.

#### Multi-Symbol Transceiver

Figure 5 is a block diagram of a multi-symbol transceiver 34, according to an embodiment of the present invention. Multi-symbol transceiver 34 may be incorporated into any suitable electronic device which may act as an originating device or a destination device. This includes the master device 12 and slave devices 14 described with reference to Figure 1. As depicted, multi-symbol transceiver 34 includes a multi-symbol transmitter 44 and a multi-symbol receiver 48.



Multi-symbol receiver 48 comprises two multi-symbol correlated multi-sampling (CMS) receivers 46.

Multi-symbol transceiver 34 converts between one or more streams of data  $D_j$  and a Symbol transmission signal. Data  $D_j$  may comprise a number of data bits (in series or parallel data format), each of which can have value of logic-1 or logic-0. Data  $D_j$  can be carried over a two-bit wide bus ( $j=1,0$ ) into and out of multi-symbol transceiver circuit 34. The Symbol signal is a transmission signal in which the data bits are represented by a number of symbols (e.g., symbol-00, symbol-01, symbol-10, and symbol-11 shown in Figure 2), each of which is uniquely defined by a particular combination of signal level transition and signal region. The Symbol signal can be either transmitted from or received by the electronic device into which multi-symbol transceiver 34 is incorporated. The Symbol signal is carried over a Symbol line into and out of multi-symbol transceiver 34.

In one embodiment, as depicted, multi-symbol transceiver 34 outputs and receives a SymbolB signal, which is the differential for the Symbol signal. The differential SymbolB signal is carried on a separate SymbolB line, which may be combined with the Symbol line in a twisted pair configuration. In a printed circuit board context, the Symbol signal and the differential SymbolB signal are carried on respective traces. The differential SymbolB signal carried over the SymbolB line serves to reduce the effects of electromagnetic interference (EMI) on the Symbol line. In an alternate embodiment, multi-symbol transceiver 34 may utilize a single-ended Symbol signal (i.e., without

a differential SymbolB signal and separate SymbolB line).

For a Symbol signal transmitted out of the electronic device, multi-symbol transmitter 44 formats or encodes data  $D_j$  as symbols in an outgoing signal, controls the slew rate of the signal, and drives the signal. With the encoded symbol format, data  $D_j$  can be transmitted across a Symbol bus (connecting a plurality of electronic devices) at very high data rate and more reliably than with previously developed technologies and techniques. Multi-symbol transmitter 44 receives a clock (CLK) signal (which is derived from and synchronized with a system clock) and an enable (ENB) signal. As depicted, multi-symbol transmitter 44 outputs SYMout for the outgoing Symbol signal, and may generate and output a differential SYMoutB for a respective outgoing differential SymbolB signal.

An exemplary embodiment for a multi-symbol transmitter 44 supporting or using a single-ended Symbol signal is shown and described with reference to Figure 6A. An exemplary embodiment for a multi-symbol transmitter 44 supporting or using both a Symbol signal and respective differential SymbolB signal is shown and described with reference to Figure 6B.

For a Symbol signal received by the electronic device, multi-symbol receiver 48 may receive the incoming Symbol signal as SYMin and the differential SymbolB signal as SYMinB. Multi-symbol receiver 48 samples the incoming Symbol signal and recovers the real data  $D_j$  using the sampled values. In one embodiment, each multi-symbol CMS receiver 46 multi-samples the incoming Symbol signal to detect a signal

transition and a signal region for each symbol in the signal. The format of data  $D_j$  can be either double data rate (DDR) format (if the clock (CLK) signal is twice the frequency of the system clock signal) or single  
5 data rate (SDR) format (if the clock (CLK) signal is the same frequency as the system clock signal).

One of the multi-symbol CMS receivers 46 may operate on one part of an incoming Symbol transmission signal, while the other may operate on another part of  
10 the incoming Symbol signal. For example, the data  $D_j$  (represented by corresponding symbols within the Symbol signal) may be divided equally based upon positioning in a stream or sequence. Data  $D_j$  at odd-numbered positions in the sequence (i.e., first, third, fifth,  
15 etc. positions) are recovered by the first multi-symbol CMS receiver 46. Data  $D_j$  at even-numbered positions in the sequence (i.e., second, fourth, sixth, etc. positions) are recovered by the second multi-symbol CMS receiver 46.

20 Each multi-symbol receiver circuit 46 can be timed with one or more phase ( $\emptyset$ ) signals. As shown, one multi-symbol receiver circuit 46 receives a  $\emptyset 1$  signal, a  $\emptyset 2$  signal,  $\emptyset EN1$  signal, while the other multi-symbol receiver circuit 46 receives a  $\emptyset 3$  signal, a  $\emptyset 4$  signal,  
25  $\emptyset EN2$  signal. Each multi-symbol receiver circuit 46 may receive a voltage signal of a predetermined voltage, such as, for example, a bus termination voltage ( $V_{TT}$ ) signal.

A  $V_{TT}$  tracking channel circuit 47 outputs the bus  
30 termination voltage ( $V_{TT}$ ) signal through a termination resistor  $R_t$ . The bus termination voltage ( $V_{TT}$ ) signal

with a termination resistor  $R_t$  can be used to emulate or track the physical characteristics of the channel over which the incoming Symbol signal is received.

For an embodiment of multi-symbol transmitter 44 supporting or using a single-ended Symbol signal, the VTT tracking channel circuit 47 is used to provide the SymbolB signal to the SYMinB input of multi-symbol CMS receiver circuits 46 of a destination element. In this case, the voltage value for the SymbolB is approximately  $V_{TT}$ . For an embodiment for a multi-symbol transmitter 44 supporting or using both a Symbol signal and respective differential SymbolB signal, the SYMoutB signal from multi-symbol transmitter 44 is fed to the SYMinB input of the multi-symbol CMS receiver circuits 46 of a destination element.

#### Multi-Symbol Transmitter

Figure 6A is a schematic diagram, in partial block form, of a multi-symbol transmitter 44, according to an embodiment of the present invention. Multi-symbol transmitter 44, which may be a part of a multi-symbol transceiver 34, can be incorporated into an electronic device, such as, for example, a processing device or memory device. This embodiment of multi-symbol transmitter 44 supports or utilizes a single-ended Symbol signal which is output over a respective Symbol line to an appropriate receiver.

Multi-symbol transmitter 44 receives a clock (CLK) signal and an enable (ENB) signal. The clock (CLK) signal may run at twice the frequency of symbol (system) clock. Multi-symbol transmitter 44 operates on one or more streams of data to be output from the

electronic device. The data stream (which is synchronized with the clock (CLK) signal) may include a number of data bits, each of which can be a logical value of either "0" (logic-0) or "1" (logic-1). This data may be received by multi-symbol transmitter 44 in input data signals D0, D1 carried on a two-bit wide bus 62 for this embodiment.

As shown, multi-symbol transmitter 44 includes an output DC level calibration circuit 52, a driver strength control circuit 54, a multi-symbol encoder circuit 56, a first supply source 55, a second supply source 57, and a stabilization control circuit 59. These circuits and supply sources cooperate to generate a Symbol transmission signal for transferring data D0 and D1 out of the electronic device (which then would be acting as an originating device). If a serial-to-parallel conversion stage is added in between the bus 62 and multi-symbol encoder circuit 56, then the data bits on bus 62 can be in serial format instead of parallel format.

Multi-symbol encoder circuit 56 encodes incoming data D1 and D0 (appearing on bus 62) according to an embodiment of the multi-symbol signaling technique described herein. More specifically, for each set of bits D0 and D1 on bus 62, multi-symbol encoder circuit 56 generates a respective symbol 32 (e.g., symbol-00, symbol-01, symbol-10, and symbol-11). Each symbol is uniquely defined by a particular combination of signal level transition and signal region in the carrier Symbol signal. Alternatively, as previously described, each symbol may be alternatively defined by signal levels (e.g., VL, VTT, and VH) occurring at respective

halves (e.g., time periods t0 and t1) of a clock signal. In one embodiment, multi-symbol encoder circuit 56 encodes the incoming data D1 and D0 according to the table shown on Figure 7. Multi-symbol encoder circuit 56 outputs output data signals do0 and do1. Multi-symbol encoder circuit 56 receives as input signals D0, D1, CLK, and ENB. When the ENB signal is low, multi-symbol transmitter 44 is enabled so that a symbol transfer cycle may begin.

10 Driver strength control circuit 54, coupled to multi-symbol encoder circuit 56, receives the do0 and do1 signals therefrom. Driver strength control circuit 54 also receives a signal from output DC level calibration circuit 52. Driver strength control circuit 54 generates a pair of control signals ( $\emptyset P$  and  $\emptyset N$ ). Control signal  $\emptyset P$  has the same logic polarity as output data signal do1. Control signal  $\emptyset N$  has the same logic polarity as output data signal do0. In general, driver strength control circuit 54 functions to regulate or control the signal levels (e.g., VL and VH) of the Symbol signal for transmitting the symbols via a suitable channel. To accomplish this, driver strength control circuit 54 may control a suitable driver circuit (as described below).

25 Stabilization control circuit 59 is also coupled to multi-symbol encoder circuit 56, and receives the do0 and do1 signals therefrom. Stabilization control circuit 59 comprises an inverter 81, a NAND gate 83, and an inverter 85. Inverter 81 receives the do0 signal. NAND gate 83 receives the output signal of inverter 81 at one input and the do1 signal at another input. NAND gate 83 outputs a control signal  $\emptyset PE$ .

Inverter 85 receives the output signal of NAND gate 83 and outputs a control signal  $\emptyset N_E$ . Control signals  $\emptyset P_E$  and  $\emptyset N_E$  generally serve to control circuitry which is used to stabilize particular nodes in the driver circuit of multi-symbol transmitter 44.

An exemplary driver circuit may be implemented as a driver circuit comprising a first transistor 49, a second transistor 50, first supply source 55, and second supply source 57. As depicted, transistor 49 comprises a PMOS transistor and transistor 50 comprises an NMOS transistor. Transistors 49 and 50 are coupled together at their drains. The source of transistor 49 is coupled to the first supply source 55 at a node  $N_H$ , and the source of the transistor 50 is coupled to the second supply source 57 at a node  $N_L$ . The gates of transistor 49 and transistor 50 receive the  $\emptyset P$  and  $\emptyset N$  signals, respectively. As such, the  $\emptyset P$  and  $\emptyset N$  signals serve as control signals for transistor 49 and transistor 50.

A pair of transistors 51 and 53 are also coupled between supply sources 55 and 57. As depicted, transistor 51 comprises a PMOS transistor and transistor 53 comprises an NMOS transistor. Transistors 49 and 50 are coupled together at their drains. The source of transistor 51 is coupled to supply source 55, and the source of the transistor 53 is coupled to supply source 57. The gate of transistor 51 receives control signal  $\emptyset P_E$  and the gate of transistor 53 receives control signal  $\emptyset N_E$ . In general, these transistors 51 and 53 serve to stabilize the voltages at nodes  $N_H$  and  $N_L$ .

In one embodiment, each of supply sources 55 and 57 can be constant current sources. In this case, transistors 49 and 50 act as "switching transistors." Transistors 49 and 51 may have the same size; 5 transistors 50 and 53 may have the same size. Transistors 49 and 50 form the push-pull switching transistors for the multi-symbol transmitter 44.

When control signal  $\emptyset P$  is low (GND), transistor 49 is turned on to connect the Symbol bus to supply source 10 55, thereby driving the Symbol bus to  $V_H$  level; when control signal  $\emptyset P$  is high ( $V_{CC}$ ), transistor 49 is turned off. When control signal  $\emptyset N$  is high, transistor 50 is turned on to connect the Symbol bus to supply source 57, thereby driving the Symbol bus to  $V_L$  level; 15 when control signal  $\emptyset N$  is low, transistor 50 is turned off.

When control signal  $\emptyset N$  is low and control signal  $\emptyset P$  is high, the push-pull switching transistors 49 and 50 are turned off and both supply source 55 and supply 20 source 57 are disconnected from the Symbol bus. At this moment, the predetermined voltage (e.g., termination voltage  $V_{TT}$ ) will pull the Symbol bus to  $V_{TT}$  level through termination resistor  $R_T$ . Supply source stabilizing transistors 51 and 53 are turned on to 25 maintain roughly the same voltage levels at nodes  $N_H$  (e.g.,  $V_{sath}$ ) and  $N_L$  (e.g.,  $V_{satL}$ ), respectively, as with a previous operation for transmitting a symbol (i.e., either supply source 55 driving the bus to  $V_H$  through transistor 49, or supply source 57 driving the 30 bus to  $V_L$  through transistor 50). This ensures signal integrity for the next symbol because both nodes  $N_H$  and



NL start at roughly the same voltage levels for each transfer operation.

Transistors 51 and 53 are controlled by signals  $\emptyset PE$  and  $\emptyset NE$ , respectively. These control signals  $\emptyset PE$  and  $\emptyset NE$  are generated by stabilization control circuit 59, which receives do0 and do1 as input signals. When the do0 signal is logic-0 and the do1 signal is logic-1 (in which case both transistors 49 and 50 are turned off), control signal  $\emptyset PE$  is logic-0 and control signal  $\emptyset NE$  is logic-1. This turns on transistors 51 and 53, thus forming a current path between nodes NH and NL to maintain both nodes roughly at  $V_{satH}$  and  $V_{satL}$ , respectively.

At power up, output DC level calibration circuit 52 automatically generates test data patterns to determine proper magnitudes of current at supply source 55 and supply source 57, and proper sizes of transistors 49, 51, 50, and 53 to ensure proper DC levels of  $V_H$  and  $V_L$  for a given channel (i.e., Symbol bus). Transistors 49, 51, 50, and 53 may actually comprise multiple programmable transistors with the same drive strengths to give incremental DC level adjustments on the  $V_H$  and  $V_L$ . Output DC level calibration circuit 52 registers information on the selected sizes of supply source 55 and supply source 57, and the transistor size information of transistors 49, 51, 50, and 53 in a register (not shown) contained in driver strength control circuit 54.

In operation, when the enable (ENB) signal is low, multi-symbol transmitter 44 is enabled to begin a symbol transfer cycle. During the symbol transfer cycle, multi-symbol transmitter 44 drives the Symbol

bus through the push-pull driver circuit. Driver strength control circuit 54 utilizes the information contained in its size register, in combination with the do0 and dol signals from multi-symbol encoder circuit 56, to determine the suitable strengths for the constant current sources implementing supply sources 55 and 57, and the number of transistors 49 and 50 to be used to drive the Symbol bus. The strength control is achieved by using multiples of each of control signals ØP and ØN (only shown as single signals in Figure 6A). Control signal ØP controls transistor 49 and supply source 55, and control signal ØN controls transistor 50 supply source 57.

In the symbol transfer cycle, multi-symbol transmitter 44 drives the Symbol bus. At the other end of the Symbol bus, termination resistor  $R_t$  and termination voltage  $V_{TT}$  minimize the reflection caused by the transmission line effect of the channel, thus ensuring proper signal integrity for the receivers of any device (e.g., slave device-1 to slave device-k) to read the transmitted symbols properly.

In the case of  $D_1=0$  and  $D_0=0$ , at a time period  $t_0$  (during CLK high time),  $do0=\text{ØN}$  has a value of logic-1 and  $dol=\text{ØP}$  has a value of logic-1 (see Figures 7 and 8). Transistor 50 will be turned on and transistor 49 will be turned off, thus setting the signal level on the Symbol bus voltage to  $V_L$  level during CLK high time. At a time period  $t_1$  (during CLK low time),  $do0=\text{ØN}$  has a value of logic-0 and  $dol=\text{ØP}$  has a value of logic-1 (see Figures 7 and 8). Transistors 50 and 49 will be turned off, thus setting the signal level on the Symbol bus to  $V_{TT}$  level during CLK low time.

Transistors 51 and 53 both turn on to form a current path between nodes NH and NL to maintain both nodes roughly at  $V_{sath}$  and  $V_{satL}$ , respectively.

In the case of  $D1=0$  and  $D0=1$ , at a time period  $t_0$  (during CLK high time),  $do0=\emptyset N$  has a value of logic-0 and  $dol=\emptyset P$  has a value of logic-1 (see Figures 7 and 8). Transistors 50 and 49 will both be turned off, thus setting the signal level on the Symbol bus to  $V_{TT}$  during CLK high time. Transistors 51 and 53 are both turned on, thus forming a current path between nodes NH and NL to maintain both nodes roughly at  $V_{sath}$  and  $V_{satL}$ , respectively. At a time period  $t_1$  (during CLK low time),  $do0=\emptyset N$  has a value of logic-0 and  $dol=\emptyset P$  has a value of logic-0 (see Figures 7 and 8). Transistor 50 will be turned off and transistor 49 will be turned on, thus setting the signal level on the Symbol bus to  $V_H$  during CLK low time.

In the case of  $D1=1$  and  $D0=0$ , at a time period  $t_0$  (during CLK high time),  $do0=\emptyset N$  has a value of logic-0 and  $dol=\emptyset P$  has a value of logic-1 (see Figures 7 and 8). Transistors 50 and 49 will both be turned off, thus setting the signal level on the Symbol bus to  $V_{TT}$ . Transistors 51 and 53 are both turned on to form a current path between nodes NH and NL to maintain both nodes roughly at  $V_{sath}$  and  $V_{satL}$ , respectively. At a time period  $t_1$  (during CLK low time),  $do0=\emptyset N$  has a value of logic-1 and  $dol=\emptyset P$  has a value of logic-1 (see Figures 7 and 8). Transistor 50 will be turned on and transistor 49 will be turned off, thus setting the signal level on the Symbol bus to  $V_L$ .

In the case of  $D1=1$  and  $D0=1$ , at a time period  $t_0$  (during CLK high time),  $do0=\emptyset N$  has a value of logic-0

and  $do1=\emptyset P$  has a value of logic-0 (see Figures 7 and 8). Transistor 50 will be turned off and transistor 49 will be turned on, thus setting the signal level on the Symbol bus to  $V_H$ . At a time period  $t_1$  (during CLK low time),  $do0=\emptyset N$  has a value of logic-0 and  $do1=\emptyset P$  has a value of logic-1 (see Figures 7 and 8). Transistors 50 and 49 will both be turned off, thus setting the signal level on the Symbol bus to  $V_{TT}$ . Transistors 51 and 53 are both turned on, thus forming a current path between nodes NH and NL to maintain both nodes roughly at  $V_{satH}$  and  $V_{satL}$ , respectively.

In an alternate embodiment which supports or utilizes a single-ended Symbol signal, supply source 55 can be voltage source  $V_{CC}$  and supply source 57 can be ground (GND). In such case, at power up, output DC level calibration circuit 52 automatically generates test data patterns to determine the proper sizes of transistors 49 and 50 to ensure proper DC levels of  $V_H$  and  $V_L$  for a given channel (i.e., the Symbol bus). Transistors 49 and 50 can be driver transistors. Transistors 49 and 50 may actually comprise multiple programmable transistors with the different drive strengths to give incremental DC level adjustments on the  $V_H$  and  $V_L$ . Output DC level calibration circuit 52 registers information on sizes of transistors 49 and 50 in a register (not shown) contained in driver strength control circuit 54. In this case, because node NH is connected to  $V_{CC}$  and node NL is connected to ground, transistors 51 and 53 are not needed to stabilize the voltages at these two nodes between different operations (i.e., either for actively driving symbol bus to  $V_H$  or  $V_L$ , or allowing the predetermined voltage

(e.g., termination voltage  $V_{TT}$ ) to determine the bus voltage).

During the symbol transfer cycle, driver strength control circuit 54 utilizes the information contained  
5 in its size register, in combination with the do0 and do1 signals from the multi-symbol encoder circuit 56, to determine the number of transistors 49 and 50 for the push-pull driver to be used to drive the Symbol bus.

10 In yet an alternate embodiment which supports or utilizes a single-ended Symbol signal, supply source 55 can be a constant voltage source VC1 and supply source 57 can be a constant voltage source VS1. At power up, output DC level calibration circuit 52 automatically  
15 generates test data patterns to determine the proper sizes for transistors 49 and 50 to ensure proper DC levels of  $V_H$  and  $V_L$  for a given channel (i.e., the Symbol bus). Transistors 49 and 50 can be driver transistors. Transistors 49 and 50 may actually  
20 comprise multiple programmable transistors with the different drive strengths to give incremental DC level adjustments on the  $V_H$  and  $V_L$ . Output DC level calibration circuit 52 registers the information regarding the sizes of transistors 49 and 50 in the  
25 size register contained in driver strength control circuit 54. In this case, because node NH is connected to constant voltage source VC1 and node NL is connected to constant voltage source VS1, transistors 51 and 53 are not needed to stabilize the voltages at these two  
30 nodes between different operations (i.e., either for actively driving symbol bus to  $V_H$  or  $V_L$ , or allowing the

predetermined voltage (e.g., termination voltage  $V_{TT}$ ) to determine the bus voltage).

During the symbol transfer cycle, driver strength control circuit 54 utilizes the information contained  
5 in its size register, in combination with the do0 and do1 signals from the multi-symbol encoder circuit 56, to determine the number of transistors 49 and 50 for the push-pull driver to be used to drive the Symbol bus.

10 Figure 6B is a schematic diagram, in partial block form, of an alternate embodiment for multi-symbol transmitter 44. This embodiment of multi-symbol transmitter 44 supports or utilizes a Symbol signal and differential SymbolB signal, which are carried over a  
15 Symbol line and SymbolB line, respectively.

Similar to the embodiment shown in Figure 6A, this embodiment of multi-symbol transmitter 44 shown in Figure 6B includes an output DC level calibration  
20 circuit 52, a driver strength control circuit 54, a multi-symbol encoder circuit 56, a first supply source 55, a second supply source 57, and a stabilization control circuit 59. These circuits 52, 54, 56, and 59 and power sources 55 and 57 operate essentially the same as previously described with reference to Figure  
25 6A. This embodiment of multi-symbol transmitter 44 also includes an exemplary driver circuit (comprising transistors 49 and 50 coupled between supply sources 55 and 57), and stabilizing transistors 51 and 53.

Multi-symbol transmitter 44 also includes a pair  
30 of transistors 71 and 73 (coupled between supply sources 55 and 57) and inverters 75 and 77. Inverter 75 receives the control signal  $\emptyset N$  at its input, and

inverter 77 receives the control signal  $\emptyset P$  at its input. Transistor 71 may comprise a PMOS transistor, and transistor 73 may comprise an NMOS transistor. Transistors 71 and 73 are coupled together at their drains. The source of transistor 71 is coupled to supply source 55, and the source of the transistor 73 is coupled to supply source 57. The gate of transistor 71 receives the output signal from inverter 75, and the gate of transistor 73 receives the output signal from inverter 77. In general, transistors 71 and 73 and inverters 75 and 77 cooperate to support the generation and driving of the differential signal SymbolB, which is output as signal SYMoutB at the junction of transistors 71 and 73. Transistors 71 and 73, in combination with supply sources 55 and 57, may constitute a differential output driver circuit.

In one embodiment of multi-symbol transmitter 44 which supports or utilizes a Symbol signal and differential SymbolB signal, each of supply sources 55 and 57 can be constant current sources. Transistors 49, 73 and 71, 50 form the differential push-pull switching transistors for multi-symbol transmitter 44. Transistors 49, 51, and 71 may have the same size; transistors 50, 53, and 73 may have the same size.

When control signal  $\emptyset P$  is low (GND), transistor 49 is turned on to connect the Symbol bus to supply source 55, thereby driving the Symbol bus to  $V_H$  level; transistor 73 is also turned on to connect supply source 57 to drive the SymbolB bus to  $V_L$  level. When control signal  $\emptyset P$  is high ( $V_{CC}$ ), transistors 49 and 73 are turned off. When control signal  $\emptyset N$  is high, transistors 50 and 71 are turned on to connect the

Symbol and SymbolB buses to supply sources 57 and 55, respectively. Thus, the Symbol bus is driven to VL level, and the SymbolB bus is driven to VH level. When control signal  $\emptyset N$  is low, the transistors 50 and 71 are  
5 turned off.

When control signal  $\emptyset N$  is low and control signal  $\emptyset P$  is high, push-pull switching transistors 49, 50, 71, 73 are turned off and both supply source 55 and supply source 57 are disconnected from the Symbol bus and  
10 SymbolB bus. At this moment, the predetermined voltage (e.g., termination voltage  $V_{TT}$ ) will pull both the Symbol bus and SymbolB bus to  $V_{TT}$  level through termination resistors  $R_T$ . Supply source stabilizing transistors 51 and 53 are turned on to maintain roughly  
15 the same voltage levels at nodes NH (e.g.,  $V_{sath}$ ) and NL (e.g.,  $V_{satL}$ ), respectively, as with a previous operation for transmitting a symbol. This ensures signal integrity for the next symbol because both nodes NH and NL start at roughly the same voltage levels for  
20 each transfer operation.

Transistors 51 and 53 are controlled by signals  $\emptyset PE$  and  $\emptyset NE$ , respectively. These control signals  $\emptyset PE$  and  $\emptyset NE$  are generated by stabilization control circuit 59, which receives  $do0$  and  $do1$  as input signals. When  
25 the  $do0$  signal is logic-0 (in which case transistors 50 and 71 are turned off) and the  $do1$  signal is logic-1 (in which case transistors 49 and 73 are turned off), control signal  $\emptyset PE$  is logic-0 and control signal  $\emptyset NE$  is logic-1. This turns on transistors 51 and 53, thus  
30 forming a current path between nodes NH and NL to maintain both nodes roughly at  $V_{sath}$  and  $V_{satL}$ , respectively.



At power up, output DC level calibration circuit 52 automatically generates test data patterns to determine proper magnitudes of current at supply source 55 and supply source 57, and proper sizes of  
5 transistors 49, 50, 51, 53, 71, and 73 to ensure proper DC levels of VH and VL for given channel (i.e., Symbol bus and SymbolB bus). Transistors 49, 50, 51, 53, 71, and 73 may actually comprise multiple programmable transistors with the same drive strengths to provide  
10 incremental DC level adjustments on the VH and VL. Output DC level calibration circuit 52 registers information on the selected sizes of supply source 55 and supply source 57, and the transistor size information of transistors 49, 50, 51, 53, 71, and 73  
15 in a register (not shown) contained in driver strength control circuit 54.

In operation, when the enable (ENB) signal is low, multi-symbol transmitter 44 is enabled to begin a symbol transfer cycle. During the symbol transfer  
20 cycle, multi-symbol transmitter 44 drives the Symbol and SymbolB buses through the push-pull driver circuits (comprising supply sources 55 and 57 in combination with transistors 49 and 50 for the Symbol bus and transistors 71 and 73 for the SymbolB bus). Driver  
25 strength control circuit 54 utilizes the information contained in its size register, in combination with the do0 and do1 signals from multi-symbol encoder circuit 56, to determine the suitable strengths for the constant current sources implementing supply sources 55  
30 and 57, and the number of transistors 49, 50, 51, 53, 71, and 73 to be used to drive the Symbol and SymbolB buses. The strength control is achieved by using

multiples of each of control signals  $\emptyset P$  and  $\emptyset N$  (only shown as single signals in Figure 6B). Control signal  $\emptyset P$  controls transistors 49 and 73 and supply source 55, and control signal  $\emptyset N$  controls transistors 50 and 71  
5 and supply source 57.

Multi-symbol encoder circuit 56 encodes incoming data D1 and D0 (appearing on bus 62) according to an embodiment of the multi-symbol signaling technique described herein. Multi-symbol encoder circuit 56  
10 receives as input signals D0, D1, CLK, and ENB. When the ENB signal is low, the differential multi-symbol transmitter 44 is enabled, and the symbol transfer cycle may begin. Multi-symbol transmitter 44 will drive the Symbol bus and SymbolB bus to transmit  
15 "differential" symbols according to the waveforms illustrated in Figure 6C for four different symbols. The other end of the Symbol bus or SymbolB bus is terminated with a termination resistor  $R_T$  and a predetermined voltage (e.g., termination voltage  $V_{TT}$ ) to  
20 minimize the reflection caused by the transmission line effect of the channel. This ensures signal integrity for the receivers of any slave devices to read the transmitted "differential" symbols properly.

In the case of  $D1=0$  and  $D0=0$ , at a time period  $t_0$   
25 (during CLK high time)  $do0=\emptyset N$  has a value of logic-1 and  $do1=\emptyset P$  has a value of logic-1 (see Figures 7 and 8). Transistors 50 and 71 will be turned on and transistors 49 and 73 will be turned off, thus setting the signal level on Symbol bus voltage to  $V_L$  and the  
30 signal level on SymbolB bus to  $V_H$  during CLK high time. At a time period  $t_1$  (during CLK low time),  $do0=\emptyset N$  has a value of logic-0 and  $do1=\emptyset P$  has a value of logic-1 (see

Figures 7 and 8). Each of transistors 49, 50, 71, 73 will be turned off, thus setting the signal levels of the Symbol bus and SymbolB bus to  $V_{TT}$  during CLK low time. Transistors 51 and 53 are both turned on, thus  
5 forming a current path between nodes NH and NL to maintain both nodes roughly at  $V_{sath}$  and  $V_{satL}$ , respectively.

In the case of  $D1=0$  and  $D0=1$ , at a time period  $t_0$  (during CLK high time),  $do0=\emptyset N$  has a value of logic-0  
10 and  $dol=\emptyset P$  has a value of logic-1 (see Figures 7 and 8). Transistors 49, 50, 71, 73 will all be turned off, thus setting the signal level on both the Symbol bus and SymbolB bus to  $V_{TT}$  during CLK high time. Transistors 51 and 53 are both turned on, thus forming  
15 a current path between nodes NH and NL to maintain both nodes roughly at  $V_{sath}$  and  $V_{satL}$ , respectively. At a time period  $t_1$  (during CLK low time),  $do0=\emptyset N$  has a value of logic-0 and  $dol=\emptyset P$  has a value of logic-0 (see Figures 7 and 8). Transistors 50 and 71 will be turned  
20 off and transistors 49 and 73 will be turned on, thus setting the signal level on the Symbol bus voltage to  $V_H$  and the signal level on the SymbolB bus to  $V_L$  during CLK low time.

In the case of  $D1=1$  and  $D0=0$ , at a time period  $t_0$   
25 (during CLK high time),  $do0=\emptyset N$  has a value of logic-0 and  $dol=\emptyset P$  has a value of logic-1 (see Figures 7 and 8). Transistors 49, 50, 71, and 73 will all be turned off, thus setting the signal level on both the Symbol bus and SymbolB bus to  $V_{TT}$  during CLK high time. Transistors 51 and 53 are both turned on, thus forming  
30 a current path between nodes NH and NL to maintain both nodes roughly at  $V_{sath}$  and  $V_{satL}$ , respectively. At a

time period  $t_1$  (during CLK low time),  $do0=\emptyset N$  has a value of logic-1 and  $dol=\emptyset P$  has a value of logic-1 (see Figures 7 and 8). Transistors 50 and 71 will be turned on and transistors 49 and 73 will be turned off, thus  
5 setting the signal level on the Symbol bus to  $V_L$  and the signal level on the SymbolB bus to  $V_H$  during CLK low time.

In the case of  $D1=1$  and  $D0=1$ , at a time period  $t_0$  (during CLK high time),  $do0=\emptyset N$  has a value of logic-0  
10 and  $dol=\emptyset P$  has a value of logic-0 (see Figures 7 and 8). Transistors 50 and 71 will be turned off and transistors 49 and 73 will be turned on, thus setting the signal level on the Symbol bus voltage to  $V_H$  and the signal level on the SymbolB bus to  $V_L$  during CLK  
15 high time. At a time period  $t_1$  (during CLK low time),  $do0=\emptyset N$  has a value of logic-0 and  $dol=\emptyset P$  has a value of logic-1 (see Figures 7 and 8). Transistors 49, 50, 71, 73 will all be turned off, thus setting the signal level on both the Symbol bus and the SymbolB bus to  $V_{TT}$   
20 during CLK low time. Transistors 51 and 53 are both turned on, thus forming a current path between nodes  $N_H$  and  $N_L$  to maintain both nodes roughly at  $V_{satH}$  and  $V_{satL}$ , respectively.

In an alternate embodiment of multi-symbol  
25 transmitter 44 which supports or utilizes a differential signal, supply source 55 can be voltage source  $V_{cc}$  and supply source 57 can be ground (GND). In yet another alternate embodiment of the differential multi-symbol transmitter 44, supply source 55 can be a  
30 constant voltage source  $V_{C1}$  and supply source 57 can be a constant voltage source  $V_{S1}$ . These alternate embodiments operate in like manner to the similarly

configured embodiments for the single-ended multi-symbol transmitter described above with reference to Figure 6A.

## 5 Multi-Symbol Encoder

Figure 7 is a logic diagram of a multi-symbol encoder circuit 56, in accordance with an embodiment of the present invention. Multi-symbol encoder circuit 56 receives a clock (CLK) input signal and an enable (ENB) input signal along with the input data bits D0 and D1 and generates encoded output data signals do0 and do1. Accompanying the schematic diagram of multi-symbol encoder circuit 56 is a corresponding truth table that illustrates the output values for the various input and clock values.

Multi-symbol encoder circuit 56 comprises a plurality of inverters 64, 66, 68, 82, and 84, a plurality of NAND gates 70, 72, 74, 76, 78, 80, and 86, and a NOR gate 88. NAND gates 70, 72, and 80, and inverter 82, along with NOR gate 88 provide the encoding logic for output data signal do0. NAND gates 74, 76, 78, and 86 provide the encoding logic for output data signal do1. In operation, NAND gates 70 and 74 receive the CLK signal, while NAND gates 72 and 76 receive the inverted CLK signal (CLKB) provided by inverter 64. NAND gates 74 and 76 receive the signal for data bit D0, while NAND gates 70 and 72 receive the signal for inverted data bit D0 (D0B) provided by inverter 68. NAND gates 72 and 74 receive the signal for data bit D1, while NAND gates 70 and 76 receive the signal for inverted data bit D1 (D1B) provided by inverter 66. NAND gate 78 receives the output signals

from NAND gates 74 and 76 and provides an output signal to NAND gate 86. NAND gate 80 receives the output signals from NAND gates 70 and 72 and provides an output signal to inverter 82, whose output signal goes to NOR gate 88. NAND gate 86 receives the output signal from NAND gate 78 and an inverted ENB signal (EN), provided by inverter 84, and outputs data signal do1. NOR gate 88 receives the output signal from inverter 82 and the ENB signal and outputs data signal do0. When the ENB input signal goes to a low voltage level or a logic-0 value, multi-symbol encoder circuit 56 is enabled to encode the incoming data bits D0 and D1 to generate proper do0 and do1 logic. This is illustrated in the truth table of Figure 7 during the time periods t0 and t1 when the CLK signal is at a high logic level and low logic level, respectively.

As an example of the circuit operation for data bits D1=1 and D0=0, when the CLK signal is high, NAND gate 76 receives the signal for data bit D0, the inverted CLK signal, and the inverted signal for data bit D1 and outputs a high voltage or a logic-1 value. NAND gate 74 receives the signal for data bit D0, the CLK signal, and the signal for data bit D1 and outputs a logic-1 value. NAND gate 78 receives a logic-1 value from NAND gates 74 and 76 and outputs a low voltage level or a logic-0 value. NAND gate 86 receives the logic-0 value from NAND gate 78 and, if the ENB signal is low, outputs a logic-1 value, which is shown in the truth table of Figure 7 for do1 at time period t0 with CLK signal high.

NAND gate 72 receives the signal for data bit D1, the inverted CLK signal, and the inverted signal for

data bit D0 and outputs a logic-1 value. NAND gate 70 receives the CLK signal and inverted signals for data bits D0 and D1 and outputs a logic-1 value. NAND gate 80 receives the logic-1 value outputs from NAND gates 70 and 72 and outputs a logic-0 value, which is inverted by inverter 82 to output a logic-1 value. NOR gate 88 receives the logic-1 value from inverter 82 and, if ENB signal is low, outputs a logic-0 value, which is shown in the truth table of Figure 7 for do0 at time period t0 with CLK signal high. A similar analysis would be understood for the remaining values in the truth table.

#### 15 Timing Diagram For Multi-Symbol Encoder

Figure 8 is a timing diagram 118 corresponding to the multi-symbol encoder of Figure 7. In accordance with an embodiment of the present invention, timing diagram 118 illustrates the timing for a multi-symbol encoder circuit 56 that receives input signals for data bits D0 and D1, along with a clock (CLK) signal and an enable (ENB) signal, and generates encoded output data signals do0 and do1.

Timing diagram 118 includes exemplary waveforms for various signals including symbol clock signal 135, CLK signal 120, ENB signal 122, data bit signals D1 124 and D0 125, output data signals do0 127 and do1 129, transmitted Symbol signal 132, transmitted differential symbolB signal 133, and the original data bit signals D1 134 and D0 136 recovered at a receiver (e.g., multi-symbol receiver 48). These waveforms illustrated in timing diagram 118 of Figure 8 are provided to

facilitate an understanding of the timing associated with multi-symbol encoder circuit 56 and serve to summarize an exemplary timing for the designated data, as described further herein.

5        Symbol clock signal 135, which is input into DLL and control timing generator 31, is synchronized with the external system clock signal. CLK signal 120 is derived from the symbol clock signal 135 by DLL and control timing generator 31 and serves as the master  
10 clock signal to synchronize, among other things, the transfer and processing of the symbols. ENB signal 122, as described above, initiates the symbol transfer cycle when it drops to a low voltage level or a logic-0 value. The data bit signals 124 and 125 illustrate  
15 exemplary data values for data bits D1 and D0 at the input to the multi-symbol transmitter 44 (as discussed in detail with reference to Figures 6A and 6B). As an example, the values for data bits D1 and D0 are shown as 10, 11, 01, 00, 10, and 11 for D1 and D0,  
20 respectively, over a number of clock cycles. These values are encoded by multi-symbol encoder circuit 56, which outputs data signals do0 127 and do1 129 (as discussed in detail in reference to Figure 7).

      Data signals do0 127 and do1 129, which correspond  
25 to control signals  $\emptyset$ N and  $\emptyset$ P as described above with reference to Figures 6A and 6B, are used to generate the symbols in Symbol signal 132, transmitted on the Symbol bus or communication channel. Each symbol may appear as a respective waveform in Symbol signal 132.  
30 As depicted, these symbols include, in sequence, symbol-10, symbol-11, symbol-01, symbol-00, symbol-10, and symbol-11. Differential symbolB signal 133



provides a differential single for symbol signal 132. The exemplary symbols illustrated for Symbol signal 132 are recognized by a receiver based upon a voltage transition and region relative to a pre-determined voltage level, such as  $V_{TR}$ , as discussed in detail herein. Symbol signal 132 is received by multi-symbol receiver 46, which generates data bit signals D1 134 and D0 136, to recover data bits D1 and D0, as discussed in detail below. As shown, data bit signals D1 134 and D0 136 correspond to the original data bit signals D1 124 and D0 126, but delayed one or more clock cycles depending upon the length and delays associated with the communication channel.

#### 15 Multi-Symbol CMS Receiver

Figure 9 is a block diagram of a multi-symbol correlated multi-sampling (CMS) receiver 46 in accordance with an embodiment of the present invention. Multi-symbol CMS receiver 46 comprises a pre-amplifier 310, two region detectors 320, and two transition detectors 370, which provide for the reception of the incoming symbol signals. Pre-amplifier 310 receives the incoming symbol stream and converts the symbols into differential signals (e.g.,  $Q+$  and  $Q-$ ), as described in more detail below. Region detectors 320 and transition detectors 370 translate and decode the incoming differential signals into the correct  $N$ -bit data polarity according to a defined truth table. In this exemplary embodiment,  $N$  equals 2 and multi-symbol CMS receiver 46 receives the incoming symbols and outputs the two-bit data having the correct polarity according to the truth table defined herein. As shown

in Figure 9 and described in more detail below, this exemplary embodiment provides two region detectors 320 and two transition detectors 370, with one region detector 320 and one transition detector 370 processing the data during odd-numbered clock signals and one region detector 320 and one transition detector 370 processing the data during even-numbered clock signals. This provides interleaved symbol sampling that allows for a high clock and data rate operation.

For an embodiment in which differential signals (Symbol and SymbolB) are used for transmitting data, pre-amplifier 310 receives input signals SYMin, SYMinB, and voltage Vbias, and provides output signals Q+ and Q-. The input signal SYMin provides the symbols necessary to ultimately derive the values of data bits D0 and D1. The input signal SYMinB is the differential for the signal, while the voltage Vbias is a bias voltage provided by a Vbias generator 311. In an alternate embodiment, in which a single-ended Symbol signal is used for transmitting data, voltage VTT may be provided at one input of pre-amplifier 310 instead of the SYMinB signal. The voltage VTT may provide a termination reference voltage from a tracking channel that indicates the channel characteristics for the Symbol bus. An exemplary embodiment of pre-amplifier 310 is illustrated and described in detail with reference to Figure 10.

Vbias generator 311, which may provide process, voltage, and temperature (PVT) compensation, generates voltage Vbias. The output signals Q+ and Q- represent the differential symbol information derived from input

signal SYMin, with these output signals provided to region detectors 320 and transition detectors 370.

Region detectors 320, with one provided to process the symbols during odd-numbered clock signals and one provided to process the symbol during even-numbered clock signals, receives the signals Q+ and Q- along with the corresponding control or phase signals for odd or even-numbered processing. The phase signals Ø1, Ø2, and ØEN1 correspond to the odd-numbered clock cycles while the phase signals Ø3, Ø4, and ØEN2 correspond to the even-numbered clock cycles. The phase signals Ø1, Ø2, Ø3, Ø4 correspond to one-cycle clock times and are phase-shifted to provide the timing for sampling the incoming symbols. Region detector 320 generally functions to determine the defining signal region within which each symbol for transmitting data lies. To accomplish this, in one embodiment, region detector 320 may sample and average the voltage levels of the incoming symbols so as to detect and amplify the least significant bit (i.e., D0) of the two data bits (i.e., D1 and D0) encoded by the transmitter, discussed above, and output the appropriate data values. An exemplary embodiment of region detector 320 is illustrated and described in detail with reference to Figure 12.

Transition detector 370, with one provided to process the symbol during odd-numbered clock signals and one provided to process the symbol during even-numbered clock signals, receives the signals Q+ and Q- along with the corresponding phase signals for odd or even-numbered processing. The phase signals Ø1, Ø2,

and  $\emptyset_{EN1}$  correspond to the odd-numbered clock cycles while the phase signals  $\emptyset3$ ,  $\emptyset4$ , and  $\emptyset_{EN2}$  correspond to the even-numbered clock cycles. The phase signals  $\emptyset_{EN1}$  and  $\emptyset_{EN2}$  will provide a logical high-level signal to  
5 activate the corresponding odd or even-numbered transition detector 370 to process the incoming symbols. Transition detector 370 generally functions to determine the defining transition for each symbol for transmitting data. To accomplish this, in one  
10 embodiment, transition detector 370 may determine the direction of the transition (positive or negative) of the incoming symbols and recover the most significant bit (i.e., D1) of the two data bits (i.e., D1 and D0) encoded at the transmitter, discussed above, and output  
15 the appropriate data values. An exemplary embodiment of transition detector 370 is illustrated and described in detail with reference to Figure 11.

#### Pre-Amplifier

20 Figure 10 illustrates a schematic diagram of a pre-amplifier 310, in accordance with an embodiment of the present invention. As discussed above, pre-amplifier 310 receives input signal SYMin, differential signal SYMinB (or voltage VTT), and voltage Vbias, and  
25 provides output signals Q+ and Q-. Accompanying the schematic diagram of pre-amplifier 310 are corresponding illustrations of input and output waveforms. The input waveforms, designated SYMin Waveforms, illustrate exemplary voltage values (i.e.,  
30  $V_H$ ,  $V_{TT}$ , and  $V_L$ ) for transmitted symbols (i.e., symbol-00, symbol-01, symbol-10, and symbol-11) during clock

time periods  $t_0$  and  $t_1$ . The SYMin waveforms illustrate waveforms received at input SYMin of pre-amplifier 310. The corresponding output waveforms, designated  $Q+/Q-$  waveforms, illustrate exemplary voltage data values that are provided by pre-amplifier 310 at respective output nodes  $Q+$  and  $Q-$ . Note that the  $Q+$  values are shown as a solid line and the  $Q-$  values are shown as a dashed line. For example, SYMin waveform symbol-10 received by pre-amplifier 310 at input SYMin results in output values at  $Q+$  and  $Q-$  as shown in the  $Q+/Q-$  waveforms for symbol-10. Specifically, input signal SYMin during time period  $t_0$  is at voltage level  $V_{TT}$  and then drops to voltage level  $V_L$  for time period  $t_1$ . These values at input SYMin result in output values for signals  $Q+$  and  $Q-$  of voltage levels  $V_{QTT+}$  and  $V_{QTT-}$ , during time period  $t_0$ , and voltage level  $V_{QH}$  for signal  $Q-$  and voltage level  $V_{QL}$  for signal  $Q+$  during time period  $t_1$ . Note that, in theory, voltages levels  $V_{QTT+}$  and  $V_{QTT-}$  would be the same if transistors 301, 306, and 308 are matched; transistors 303 and 305 are matched, transistors 300 and 307 are matched; and transistors 302 and 304 are matched. In reality, however, voltage levels  $V_{QTT+}$  and  $V_{QTT-}$  are slightly increased and decreased levels, respectively, of a voltage level  $V_{QTT}$ , due to mismatches of transistors 300 through 308 in pre-amplifier 310.

Pre-amplifier 310 comprises a plurality of transistors 300-308. As shown in Figure 10, transistors 301, 306, and 308 have their sources tied together and coupled to ground. The drain of transistor 301 is connected to the source of transistor 300, which provides the output signal  $Q-$ . The drain of

transistor 308 is connected to the source of transistor 307, which provides the output signal  $Q+$ . The drains of transistors 300 and 307, along with the sources of transistors 302 and 304, are tied together and coupled to voltage source  $V_{cc}$ . The gates of transistors 302 and 304 are tied together and coupled to ground. The drain of transistor 302 is connected to the drain of transistor 303 and to the gate of transistor 300. The drain of transistor 304 is connected to the drain of transistor 305 and to the gate of transistor 307. The sources of transistors 303 and 305 are tied together and coupled to the drain of transistor 306. The pre-amplifier 310 receives input signal  $SY_{Min}$  at the gate of the transistor 303, receives input signal  $SY_{MinB}$  at the gate of the transistor 305, and receives voltage  $V_{bias}$  at the gates of transistors 301, 306, and 308.

In operation, the voltage  $V_{TR}$  is used as a reference voltage for pre-amplifier 310 to convert the incoming symbols (i.e.,  $SY_{Min}$  waveforms) into differential outputs (i.e.,  $Q+/Q-$  waveforms), which are provided to the inputs of transition detector 370 (illustrated and described in detail with reference to Figure 11) and region detector 320 (illustrated and described in detail with reference to Figure 12). This provides common-mode noise rejection capability for multi-symbol CMS receivers 46 (illustrated and described in detail with reference to Figures 5 and 9). Transistors 302-306 provide pre-amplification, for example, with an approximate gain of one, but with a very wide dynamic linear range. The output of this pre-amplification stage is provided to the gates of transistors 300 and 307, which are used to isolate the

capacitive load from the transition detectors and region detectors to increase the bandwidth of the pre-amplification stage.

Transistors 302 and 304 are used as an active load  
5 for pre-amplifier 310, with the gates of transistors  
302 and 304 grounded to generate a pre-determined gain.  
Transistors 301, 306, and 308 are used to supply a  
constant current for pre-amplifier 310. The voltage  
Vbias biases transistors 300, 301, 303, 305, 306, 307,  
10 and 308 in the saturation region to ensure a wide  
linear range operation (e.g., greater than 1 volt) for  
pre-amplifier 310. A wide linear range is a key factor  
in preventing pre-amplifier 310 from entering into  
saturation and ensuring that it can receive incoming  
15 symbols and output signals Q+ and Q- with the desired  
differential gain (e.g., a gain in the range of one to  
two). The common mode range of pre-amplifier 310 may  
also match with the common mode range of differential  
latch amplifiers 126 and 128 of transition detectors  
20 370 and region detectors 320, respectively.  
Transistors 300 and 307 are configured as source-  
follower transistors used to buffer the intermediate  
pre-amplification outputs (i.e., nodes Nc and Nd) of  
pre-amplifier 310 to avoid overloading due to  
25 transition detectors 370 and region detectors 320 and  
to produce a very high bandwidth pre-amplifier design  
for high speed input/output interface applications.

The circuit operation of pre-amplifier 310 can be  
illustrated for exemplary symbol-10 of the SYMin  
30 waveforms. During time period t0, input signal SYMin  
is at voltage level VTT. Transistors 303 and 305 have  
the same gate voltage, resulting in symmetrical

operation such that the voltage level at nodes Nc and Nd are approximately equal. Due to the source-follower configuration of transistors 300 and 307, the voltage level at the source of transistors 300 and 307 (i.e.,  
5 the voltage output for nodes Q- and Q+) will be approximately equivalent to the voltage level at nodes Nc and Nd with small deviations from  $V_{QTT}$ .

Consequently, output signals Q+ and Q- are at respective voltage levels  $V_{QTT+}$  and  $V_{QTT-}$ , which  
10 corresponds to the voltage drop across transistors 303 and 306 or transistors 305 and 306, respectively.

During time period t1, input signal SYMin is at voltage level VL, which results in the voltage level at node Nc being at a higher level than the voltage level at node  
15 Nd. Consequently, output signal Q- is at voltage level  $V_{QH}$  while output signal Q+ is at voltage level  $V_{QL}$ , which corresponds to the difference between the voltage drops across transistors 303 and 306 and transistors 305 and 306, respectively, if the gain of the source  
20 followers is equal to one.

For an embodiment in which a single-ended Symbol signal is used for transmitting data, voltage  $V_{TT}$  is received at the gate of transistor 305. In this case, the linear range of pre-amplifier 310 may be from 0.8V  
25 to 1.8V. Thus, if the voltage levels of incoming symbols to input gates 303 and 305 of pre-amplifier 310 fall into this range, then the receivers will operate properly. A suitable voltage range for  $V_{TT}$  is 1.25V to 1.35V, which is in the middle of the linear range  
30 (i.e., 0.8V to 1.8V) of pre-amplifier 310. This implies a range for  $V_H$  between 1.3V and 1.8V, and a range for  $V_L$  between 0.8V and 1.3V. Note that if  $V_{TT}$  is



1.25V,  $V_L$  is no greater than approximately 1.2V, and if  $V_{TT}$  is 1.35V,  $V_H$  is no less than approximately 1.4V. The above mentioned voltage values are for  $V_{CC}$  equal to between 2.3V and 2.7V, and  $V_{bias}$  equal to approximately 5 0.2V above  $V_{TN}$ , i.e.,  $V_{bias}$  is in the range of 0.8V to 0.85V for 0.25 $\mu$ m CMOS process technology. The minimum voltage swing between  $V_H$  and  $V_L$  should be greater than approximately 100mV, but this value is dependent on channel characteristics and application. The voltage 10 range of pre-amplifier 310 outputs  $Q^+/Q^-$  is in the range of 0.25V to 1.55V for this embodiment, i.e.,  $V_{QL}$  is approximately 0.25V and  $V_{QH}$  is approximately 1.55V.

For an embodiment in which differential signals (Symbol and SymbolB) are used for transmitting data, 15 the linear range can be essentially the same as that for the embodiment in which a single-ended Symbol signal is used--i.e., from 0.8V to 1.8V for 2.5V power supply and 0.25 $\mu$ m CMOS process technology). Furthermore, the operation of pre-amplifier 310 may be 20 essentially the same as long as the voltage levels of the incoming symbols fall within this linear range. However, with pre-amplifier 310 operating on the incoming Symbol signal with a respective differential SymbolB signal, the voltage values on the transmission 25 lines can be scaled down 50% relatively to the voltage values that would be required for a single-ended Symbol single (with no differential SymbolB signal present). Accordingly, the voltage swings of SYMoutB and SYMout can be reduced by half, thereby further reducing EMI 30 effects by requiring lower voltage values. Thus, for applications which are especially sensitive to EMI, the differential transmission signal approach is preferred

over the single-ended transmission signal approach due to the reduced signal swing and cancellation of EM radiation when the differential channels are running in parallel in PCB or in a twisted pair cable environment.

5

#### Transition Detector

Figures 11A-11D illustrate input waveforms to a transition detector 370, showing region and transition for symbol-00, symbol-01, symbol-10, and symbol-11, respectively, at time periods  $t_0$  and  $t_1$ , as discussed above with respect to Figure 2. Time period  $t_0$  is the first half cycle of the clock, and time period  $t_1$  is the second half cycle of the clock. Time period  $t_0$  can begin at the rising edge of the clock, with time period  $t_1$  beginning at the falling edge, or vice versa. Figures 11A-11D also show differential signals  $Q^-$  and  $Q^+$  from pre-amplifier 310 of Figure 10. Figures 11A-11D help illustrate the operation of a transition detector 370 for detecting data bit D1 of a two-bit symbol.

In Figure 11A, for symbol-00, at time period  $t_0$ , signal  $Q^-$  is at high voltage  $V_{QH}$ , and signal  $Q^+$  is at low voltage  $V_{QL}$ . At time period  $t_1$ , signals  $Q^-$  and  $Q^+$  go to voltage levels  $V_{QTT-}$  and  $V_{QTT+}$ , respectively. The solid trace in each of Figures 11A-11D, indicating signal  $Q^+$ , represents the desired pattern for the data bits in each symbol. Thus, as seen from Figure 11A, the solid trace has the same shape as the trace shown in Figure 2 for symbol-00. The dashed trace represents the  $Q^-$  output signal from pre-amplifier 310. Figure 11B shows the transition and region levels for symbol-01. At time period  $t_0$ , signals  $Q^+$  and  $Q^-$  are at

voltage levels  $V_{QTT-}$  and  $V_{QTT+}$ , respectively. Then, at time period  $t_1$ , signal  $Q+$  goes to high voltage  $V_{QH}$ , while signal  $Q-$  goes to low voltage  $V_{QL}$ . Note that the slope of  $Q+$  in Figures 11A and 11B is positive (or  
5 rising transition), indicating data bit  $D_1$  is 0.

Figure 11C shows the transition and region levels for symbol-10, with signal  $Q+$  going from voltage  $V_{QTT+}$  at time period  $t_0$  down to low voltage  $V_{QL}$  at time period  $t_1$ , while signal  $Q-$  goes from voltage  $V_{QTT-}$  at time  
10 period  $t_0$  up to high voltage  $V_{QH}$  at time period  $t_1$ . Figure 11D shows the slope and voltage levels for symbol-11. At time period  $t_0$ , signal  $Q+$  is at high voltage  $V_{QH}$ , while signal  $Q-$  is at low voltage  $V_{QL}$ . At time period  $t_1$ , signal  $Q+$  drops to voltage  $V_{QTT-}$ , while  
15 signal  $Q-$  rises to voltage  $V_{QTT+}$ . In both Figures 11C and 11D, the slope of  $Q+$  is negative (or falling transition), indicating that data bit  $D_1$  is 1.

For each symbol in a received signal, transition detector 370 determines the defining transition (e.g.,  
20 rising or falling) and generates data accordingly. In one embodiment, transition detector 370 identifies the direction of the transition (positive or negative slope) and generates data according to the direction of transition. For example, transition detector 370  
25 outputs a high signal (corresponding to a logic-1 value) when signal  $Q+$  exhibits a falling transition (negative slope) and signal  $Q-$  exhibits a rising transition (positive slope) transitioning from time period  $t_0$  to time period  $t_1$ , such as for symbol-10 and  
30 symbol-11. On the contrary, transition detector 370 outputs a low signal (corresponding to a logic-0 value) when the signal  $Q+$  experiences a rising transition

(positive slope) and signal Q- experiences a falling transition (negative slope) from time period t0 to time period t1, such as for symbol-00 and symbol-01.

Figures 11E-11G show portions of transition detector 370 of Figure 9, according to one embodiment of the present invention. Figure 11E is a circuit diagram of a differencing circuit 94, Figure 11F is a diagram of a differential latch amplifier 126 with a pre-charge circuit 60, and Figure 11G is a diagram of a hold circuit 96. Transition detector 370 includes two differencing circuits 94, two differential latch amplifiers 126 and pre-charge circuits 60, and two hold circuits 96. One set of circuits is utilized for the odd-numbered clock cycles and the other set is utilized for the even-numbered clock cycles. Using odd and even clock cycles allows data to be sampled in one operation and processed and decoded in a second operation. This "interleaving" allows for high clock/data rate operations. For illustration, differencing circuit 94, differential latch amplifier 126 and pre-charge circuit 60, and hold circuit 96 will be described for use with the odd-numbered clock cycles and phase signals  $\phi_1$ ,  $\phi_2$ , and  $\phi_{EN1}$ . Although not shown, a similar set of circuits is used with the even-numbered clock cycles and phase signals  $\phi_3$ ,  $\phi_4$ , and  $\phi_{EN2}$ , which are shown in the figures to illustrate their application to desired input terminals of the various circuits.

Referring to Figure 11E, differencing circuit 94 samples and stores differential signals Q+ and Q- from pre-amplifier 310 of Figure 10 at time periods t0 and t1. Differencing circuit 94 is divided into two sub-circuits 802 and 804. Sub-circuit 802 stores the value

of signal  $Q+$  in a capacitor  $C1$  at time period  $t0$  and in a capacitor  $C3$  at time period  $t1$ . Sub-circuit 804 stores the value of signal  $Q-$  in a capacitor  $C2$  at time period  $t0$  and in a capacitor  $C4$  at time period  $t1$ .

5 Sub-circuit 802 includes transistors 372 and 374, such as NMOS transistors, each having a terminal coupled to signal  $Q+$ . The gates of transistors 372 and 374 receive phase signals  $\phi1$  and  $\phi2$ , respectively, to turn transistors 372 and 374 off and on. Phase signals  $\phi1$  and  $\phi2$  can be overlapping and are generated from the symbol clock signal, which is one-half the frequency of the clock (CLK) signal. (See Figure 14 for relationships between phase signals  $\phi1$ ,  $\phi2$ ,  $\phi3$ , and  $\phi4$  with the symbol clock and clock (CLK) signals.)

15 At the falling edge of phase signal  $\phi1$  (corresponding to sampling during time period  $t0$ ), transistor 372 is turned off. As a result, the value of signal  $Q+$  at time period  $t0$ , denoted as  $Q+(t0)$ , is stored in capacitor  $C1$ , which has one plate coupled to the other terminal of transistor 372. The opposite plate of capacitor  $C1$  is coupled to ground. Capacitor  $C1$  then holds the stored value when transistor 372 is off. At the falling edge of phase signal  $\phi2$  (corresponding to sampling during time period  $t1$ ), transistor 374 is turned off. Thus, the value of signal  $Q+$  at time period  $t1$ , denoted as  $Q+(t1)$ , is stored in capacitor  $C3$ , which has one plate coupled to the other terminal of transistor 374 and the other plate coupled to ground. Again, when transistor 374 is off, capacitor  $C3$  holds the stored value.

Sub-circuit 804 is the same as sub-circuit 802, except that signal Q-, instead of signal Q+, is coupled to transistors 376 and 378. At the falling edge of phase signal Ø1, capacitor C2 stores the value of  
5 signal Q- at time period t0, denoted as Q-(t0). At the falling edge of phase signal Ø2, capacitor C4 stores the value of signal Q- at time period t1, denoted as Q-(t1).

Accordingly, for each symbol, capacitors C1-C4  
10 store a unique combination of voltages. For example, for symbol-10 (Figure 11C), at time period t0, signals Q+ and Q- are voltage levels VQTT+ and VQTT-, respectively. For some predetermined amount of time (e.g., at least half a cycle of the CLK signal) before  
15 going low during time period t0, phase signal Ø1 is high, thereby turning on transistor 372 of sub-circuit 802 and transistor 376 of sub-circuit 804. Thus, voltage values of VQTT+ and VQTT- are stored in capacitor C1 and C2, respectively, at the falling edge of phase  
20 signal Ø1. At time period t1, Q+ is at low voltage VQL, and Q- is at high voltage VQH. For some predetermined amount of time (e.g., at least half a cycle of the CLK signal) before going low during time period t1, phase signal Ø2 is high, which turns on  
25 transistors 374 and 378 of respective sub-circuits 802 and 804. This in turn allows Q+(t1), which has a value of VQL, to be stored in capacitor C3 and Q-(t1), which has a value of VQH, to be stored in capacitor C4 at the falling edge of phase signal Ø2. The values stored in  
30 capacitors C1 through C4 represent unique signal transition information of the symbol; these values may

be received at the inputs of differential latch amplifier 126.

Differential latch amplifier 126 with pre-charge circuit 60, shown in Figure 11F, includes transistors 5 380, 382, 384, and 386 (which can be N-type or NMOS transistors) having gates coupled to receive voltages stored in respective capacitors C1, C2, C3, and C4 (i.e.,  $Q+(t_0)$ ,  $Q-(t_0)$ ,  $Q+(t_1)$ , and  $Q-(t_1)$ ). Differential latch amplifier 126 amplifies voltages at 10 nodes NA and NB, which are based on the different current flow through transistors 380, 382, 384, and 386 resulting from the voltage differences at the gates of transistors 380, 382, 384, and 386. Voltages at nodes NA and NB are then applied to a latch or hold circuit 15 (discussed below with Figure 11G) to supply the desired data bit.

A first terminal, such as a source terminal, of each of transistors 380, 382, 384, and 386 is commonly coupled to one terminal of a transistor 388 (e.g., N- 20 type), with the other terminal of transistor 388 coupled to ground. Phase signal  $\phi_{EN1}$  (for odd-numbered clock cycles) is received at the gate of current source transistor 388 to allow current flow through transistors 380, 382, 384, and 386. Voltage 25 differences between the gates of transistors 380, 382, 384, and 386 generate different current flow through the transistors.

Pre-charge circuit 60, described in more detail below, charges nodes NA and NB to a logic-1 value before 30 phase signal  $\phi_{EN1}$  turns on current source transistor 388. Thus, when phase signal  $\phi_{EN1}$  is low, pre-charge circuit 60 is on and pre-charges nodes NA and NB, and

when phase signal  $\phi_{EN1}$  is high, pre-charge circuit 60 is off. Pre-charge circuit 60 brings nodes NA and NB to a "high" or logic-1 value, such as approximately the supply voltage  $V_{CC}$  minus the threshold voltage  $V_{TP}$  of P-type transistors 390 and 392, with each having a first terminal, such as the drain terminal, coupled to nodes NA and NB, respectively. Node NA is also coupled to the second terminal (such as the drain terminal) of each of transistors 380 and 386, to the first terminal (such as the drain terminal) of transistor 390, and to the gate of transistor 392. Node NB is also coupled to the second terminal (such as the drain terminal) of each of transistors 382 and 384, to the first terminal (such as the drain terminal) of transistor 392, and to the gate of transistor 390. The second terminal (such as the source terminal) of each of transistors 390 and 392 is coupled to source voltage  $V_{CC}$ .

Based on the difference of the sampled voltages  $Q_+(t_0)$ ,  $Q_-(t_0)$ ,  $Q_+(t_1)$ , and  $Q_-(t_1)$ , different magnitudes of current flow through transistors 380, 382, 384, and 386 and nodes NA and NB when transistor 388 is turned on. P-type transistors 390 and 392 increases the voltage difference between nodes NA and NB. As an illustration, symbol-00 results in  $Q_+(t_0) = V_{QL}$ ,  $Q_-(t_0) = V_{QH}$ ,  $Q_+(t_1) = V_{QTT+}$ ,  $Q_-(t_1) = V_{QTT-}$ . Because the voltage (i.e.,  $V_{QH}$ ) at the gate of transistor 382 is higher than the voltage (i.e.,  $V_{QL}$ ) at the gate of transistor 380, more current will flow through transistor 382 than through transistor 380. Transistors 384 and 386 flow through very small differential current because the differential voltages at the gates of transistors 384 and 386 are very small



(i.e.,  $V_{QTT+} - V_{QTT-}$ ). Thus, the current flow through node NB, which is coupled to transistor 382, is greater than through node NA, which is coupled to transistor 380. This causes the voltage at node NB to be pulled  
5 down toward ground from its pre-charge voltage by transistors 382, 384, and 388, while the voltage at node NA remains high. As a result, transistor 390 is turned on, which pulls the voltage at node NA to  $V_{cc}$ , while transistor 392 is turned off, which leaves the  
10 voltage at node NB low or at ground. Table 1 below lists the symbols, each symbol's corresponding values for signals Q+ and Q- at time periods t0 and t1, and the voltage levels at nodes NA and NB.

Symbol D1D0	Voltage Q+ (t0)	Voltage Q- (t0)	Voltage Q+ (t1)	voltage Q- (t1)	Logic level NA	Logic level NB
00	VQL	VQH	VQTT+	VQTT-	1	0
01	VQTT-	VQTT+	VQH	VQL	1	0
10	VQTT+	VQTT-	VQL	VQH	0	1
11	VQH	VQL	VQTT-	VQTT+	0	1

Table 1

Voltages at nodes NA and NB are then supplied to hold circuit 96, which includes cross-coupled NAND gates 106 and 108. The voltage at node NA is applied  
20 to one input of NAND gate 106, with the other input coupled to the output of NAND gate 108. The voltage at node NB is applied to one input of NAND gate 108, with the other input coupled to the output of NAND gate 106. The output of hold circuit 96 is taken at the output of  
25 NAND gate 106 and represents the data bit D1 of the

symbol. Thus, continuing with the above example, node NB is at a low voltage, which results in the output of NAND gate 108 providing a high input to NAND gate 106. Because the voltage at node NA is also high, the output of NAND gate 106, and thus data bit D1, is low. When node NA is at a logic-1 value and node NB is at a logic-0 value, data bit D1 is at a logic-0 value. Conversely, when node NA is at a logic-0 value and node NB is at a logic-1 value, data bit D1 is at a logic-1 value.

#### Region Detector

While transition detector 370 decodes the D1 data bit, a region detector 320 decodes the data bit D0. In general, region detector 320 determines the defining region within which each symbol of a carrier signal lies. In one embodiment, region detector 320 determines whether the average voltage value of a symbol is above or below a particular voltage level, such as  $V_{QTT+}/V_{QTT-}$ . As described above, a lower region (i.e., a region below  $V_{QTT+}/V_{QTT-}$ ) indicates that data bit D0 is 0, while an upper region (i.e., a region above  $V_{QTT+}/V_{QTT-}$ ) indicates that data bit D0 is 1. Figures 12A-12D are waveforms similar to those of Figures 11A-11D, except that, in addition to waveforms input to region detector 320, Figures 12A-12D also show average values of signals Q+ and Q- for each of symbol-00, symbol-01, symbol-10, and symbol-11, respectively, generated from the input signals Q+ and Q- at time periods t0 and t1. For each of Figures 12A-12D, the solid line shows the average value for Q+, designated Q+avg, and the dashed line shows the average value for

Q-, designated Q-avg. As seen from Figures 12A and 12C, data bit D0 is 0 when the value of Q+avg is below VQTT+ or VQTT- and the value of Q-avg is above VQTT+/VQTT-. From Figures 12B and 12D, data bit D0 is 1 when the value of Q+avg is above VQTT+/VQTT- and the value of Q-avg is below VQTT+/VQTT-, or when Q+avg is above Q-avg.

Figures 12E-12G show portions of region detector 320 of Figure 9, according to one embodiment of the present invention. Figure 12E is a circuit diagram of an averaging circuit 130 for generating values Q+avg and Q-avg, Figure 12F is a diagram of a differential latch amplifier 128 with a pre-charge circuit 60, and Figure 12G is a diagram of a hold circuit 96. As with the discussion of the transition detector 370, region detector 320 includes two averaging circuits 130, two differential latch amplifiers 128, and two hold circuits 96. One set is utilized for the odd-numbered clock cycles and phase signals  $\emptyset 1$ ,  $\emptyset 2$ ,  $\emptyset_{avg1}$ , and  $\emptyset_{EN1}$ , which is discussed below, and the other set is utilized for the even-numbered clock cycles and phase signals  $\emptyset 3$ ,  $\emptyset 4$ ,  $\emptyset_{avg2}$ , and  $\emptyset_{EN2}$ , which are shown as inputs to various terminals of circuits for illustration.

Averaging circuit 130 includes a first sub-circuit 902 for generating Q+avg from input signal Q+ and a second sub-circuit 904 for generating Q-avg from input signal Q-. During time period t0, phase signal  $\emptyset 1$  is high, which turns on transistors 322 and 328 in respective sub-circuits 902 and 904. A first terminal of transistor 322 receives as input signal Q+, and a first terminal of transistor 328 receives as input signal Q-. The second terminal of each of transistors

322 and 328 is coupled to a first plate of capacitors C5 and C6, respectively, with the other plate being coupled to ground. Thus, at the falling edge of phase signal  $\phi_1$ , the value of  $Q_+$  at time period  $t_0$  is stored in capacitor C5 and the value of  $Q_-$  at time period  $t_0$  is stored in capacitor C6.

Next, phase signal  $\phi_2$  goes high during time period  $t_1$ , which turns on transistor 324 of sub-circuit 902 and transistor 330 of sub-circuit 904. A first terminal of transistor 324 receives as input signal  $Q_+$ , and a first terminal of transistor 330 receives as input signal  $Q_-$ . The second terminals of transistors 324 and 330 are coupled to a first plate of respective capacitors C7 and C8, with the other plate coupled to ground. Accordingly, at the falling edge of phase signal  $\phi_2$ , the value of  $Q_+$  at time period  $t_1$  is stored in capacitor C7 and the value of  $Q_-$  at time period  $t_1$  is stored in capacitor C8. Thus, after one odd-numbered clock cycle, the voltage levels of  $Q_+$  at time period  $t_0$  ( $Q_+(t_0)$ ),  $Q_-$  at time period  $t_0$  ( $Q_-(t_0)$ ),  $Q_+$  at time period  $t_1$  ( $Q_+(t_1)$ ), and  $Q_-$  at time  $t_1$  ( $Q_-(t_1)$ ) are stored in capacitors C5-C8, respectively. For example, for the case of Figure 12A, capacitor C5 stores  $V_{QL}$ , capacitor C6 stores  $V_{QH}$ , and capacitors C7 and C8 store  $V_{QTT+}$  and  $V_{QTT-}$ , respectively.

After capacitors C5-C8 have stored the voltages of  $Q_+$  and  $Q_-$  at time periods  $t_0$  and  $t_1$ , phase signal  $\phi_{avg1}$  goes high (at the falling edge of phase signal  $\phi_2$ ), which turns on transistor 326 of sub-circuit 902 and transistor 332 of sub-circuit 904. One terminal of transistor 326 is coupled to the first plate of

capacitor C5 and the other terminal of transistor 326 is coupled to the first plate of capacitor C7, with the capacitance of capacitors C5 and C7 designed to be equal. When phase signal  $\phi_{avg1}$  is high, transistor 326 turns on and creates a voltage divider circuit. Thus, the resulting voltage at the first plate of either capacitor C5 or C7 is the average of the values stored in capacitors C5 and C7, i.e.,  $[Q+(t_0) + Q+(t_1)]/2$ , or the average of signal  $Q+$  for time periods  $t_0$  and  $t_1$ , designated  $Q+avg$ .

Similarly, for sub-circuit 904, when phase signal  $\phi_{avg1}$  goes high, transistor 332 turns on, which results in an averaging of the voltages stored in capacitors C6 and C8. The value at the first plate capacitor C6 and C8 is the average of signal  $Q-$  at time periods  $t_0$  and  $t_1$  or approximately  $[Q-(t_0) + Q-(t_1)]/2$ , designated  $Q-avg$ . Using the earlier example for symbol-00,  $Q+avg$  and  $Q-avg$  are shown as the straight solid and dashed lines, respectively, in Figure 12A.

Signals  $Q+avg$  and  $Q-avg$  from averaging circuit 130 are received at differential inputs of differential latch amplifier 128, shown in Figure 12F along with pre-charge circuit 60. Differential latch amplifier 128 increases a voltage difference at two nodes  $N_A$  and  $N_B$  resulting from the voltage difference between  $Q+avg$  and  $Q-avg$ . Signal  $Q+avg$  is received at the gate of transistor 334, and signal  $Q-avg$  is received at the gate of transistor 336. Both transistors 334 and 336 have one terminal, such as the source terminal, coupled to the drain of a current source transistor 338. The gate of transistor 338 receives the phase signal  $\phi_{EN1}$  to turn transistor 338 on and off. Also, both

transistors 334 and 336 have the other terminal coupled to pre-charge circuit 60. As discussed above and further below, when phase signal  $\phi_{EN1}$  is low, pre-charge circuit 60 charges nodes NA and NB to a "high" or logic "1" level, such as approximately the supply voltage  $V_{cc}$  minus the threshold voltage  $V_{TP}$  of P-type transistors 394 and 396. When phase signal  $\phi_{EN1}$  goes high (when signals Q+avg and Q-avg become available), the one of transistors 334 or 336 that has the higher voltage at its gate will have more current flowing through it than the other transistor. Signals Q+avg and Q-avg are biased in the common-mode range of differential latch amplifier 128, which has a lower bound voltage slightly higher than  $V_{TN}$  of transistors 334 and 336 in order to turn on transistors 334 and 336. Normally, signals Q+avg and Q-avg have voltage values no lower than approximately 0.4V to 0.5V above  $V_{TN}$  of transistors 334 and 336.

In addition, transistors 394 and 396 will amplify this current difference of nodes NA and NB. P-type transistors 394 and 396 increase the voltage difference between node NA, which is coupled to the gate of transistor 396 and a first terminal of transistor 394, and node NB, which is coupled to the gate of transistor 394 and a first terminal of transistor 396. The second terminal of transistors 394 and 396 is coupled to supply voltage  $V_{cc}$ . Thus, the one of nodes NA or NB associated with the transistor 334 or 336 that has the lower voltage applied to its gate will be pulled to  $V_{cc}$  from pre-charge voltage  $V_{cc}-V_{TP}$  or a logic-1 value, while the other node having the transistor with the higher gate voltage will be pulled low or a logic-0

value. Continuing with the above example, for symbol-  
00, the value of  $Q_{+avg}$  (applied to transistor 334) is  
below  $V_{QTT-}$  and the value of  $Q_{-avg}$  is above  $V_{QTT+}$   
(applied to transistor 336). Consequently, when  
5 transistor 338 turns on, more current flows through  
transistor 336 than through transistor 334. The  
voltage at node NB is then pulled lower from its pre-  
charge voltage (e.g., to ground), while the voltage at  
node NA remains high. This turns on transistor 394 to  
10 pull the voltage at node NA high to  $V_{CC}$  and turns off  
transistor 396 to leave the voltage at node NB  
unchanged at low or ground. Table 2 below lists the  
symbols, each symbol's corresponding values for signals  
 $Q_{+avg}$  and  $Q_{-avg}$ , and the voltage level at nodes NA and  
15 NB, where  $\Delta V$  is  $[V_{QTT+} - V_{QL}]/2$  or  $[V_{QH} - V_{QTT-}]/2$ ,  
assuming the magnitude of the difference between  $V_{QTT+}$   
and  $V_{QH}$  and between  $V_{QTT-}$  and  $V_{QL}$  is the same.  $V_{QTT}$  is  
defined as the average of  $V_{QTT+}$  and  $V_{QTT-}$ . The minimum  
value of  $\Delta V$  is typical about 50mV.

20

Symbol D1D0	Voltage $Q_{+avg}$	Voltage $Q_{-avg}$	Logic level NA	Logic level NB
00	$V_{QTT} - \Delta V$	$V_{QTT} + \Delta V$	1	0
01	$V_{QTT} + \Delta V$	$V_{QTT} - \Delta V$	0	1
10	$V_{QTT} - \Delta V$	$V_{QTT} + \Delta V$	1	0
11	$V_{QTT} + \Delta V$	$V_{QTT} - \Delta V$	0	1

Table 2

Note that for differential latch amplifier 126  
(Fig. 11F) and differential latch amplifier 128 (Fig.

12F), at least one of the two inputs to each of transistor pairs 380 and 382 (Fig. 11F), 384 and 386 (Fig. 11F), and 334 and 336 (Fig. 12F) is approximately 0.4V to 0.5V greater than the VTN of the corresponding transistor pair in order to turn on the transistors and allow the differential latch amplifiers 126 and 128 to operate properly. The voltage value 0.4V to 0.5V is determined by current source transistors 388 (Fig. 11F) and 338 (Fig. 12F).

10 The voltages at nodes NA and NB are input to latch or hold circuit 96, shown in Figure 12G, which is the same as described above in Figure 11G. The operation of hold circuit 96 is the same as with the circuit described in Figure 11G, with the output of the hold circuit of Figure 12G representing data bit D0 instead of D1. For example, with symbol-00, the voltage at node NA is high and the voltage at node NB is low. This results in the output of NAND gate 106, and therefore, the output of hold circuit 96, being at a logic-0 value representing data bit D0 of 0. Thus, a transition detector 370, which decodes data bit D1, and a region detector, which decodes data bit D0, are used in conjunction to decode a multi-bit signal D1D0.

#### 25 Pre-Charge Circuit

Figure 13 is a circuit diagram of one embodiment of pre-charge circuit 60 for use with the differential latch amplifiers 126 and 128 of Figures 11F and 12F, respectively. Pre-charge circuit 60 includes two inverters 110 and 112 to generate signals from phase signal  $\phi_{EN1}$  for operation of the circuit 60 during odd-numbered clock cycles. Note that a similar circuit is



shown for use with phase signal  $\phi_{EN2}$  for even-numbered clock cycles. When phase signal  $\phi_{EN1}$  is low (prior to the operation of differential latch amplifier 126 (Figure 11F) and differential latch amplifier 128 (Figure 12F)), the output of inverter 110, which is coupled to the gate of transistor 92, is high, thereby turning on transistor 92. Also, when phase signal  $\phi_{EN1}$  is low, the output of inverter 112, which is coupled between the output of inverter 110 and the gate of P-type transistors 100 and 93, is low, thereby turning on transistors 100 and 93. A first terminal of equalization transistors 92 and 93 is coupled to node NA, and the second terminal of transistors 92 and 93 is coupled to node NB. Nodes NA and NB are also coupled, via P-type transistors 95, 98, and 100, to supply voltage Vcc. Thus, when phase signal  $\phi_{EN1}$  is low, transistors 92, 93, 95, 98, and 100 are on, and equalization transistors 92 and 93 equalize the voltages at nodes NA and NB to 0.5Vcc initially and eventually nodes NA and NB will be pulled to Vcc-VTP from 0.5Vcc by transistors 95, 98, and 100.

A first terminal, such as the source terminal, of transistor 100 is coupled to supply voltage Vcc. Transistor 100 serves as virtual Vcc control for P-type transistors 95 and 98 to shut off the supply current from Vcc to differential latch amplifier 126 (Figure 11F) and differential latch amplifier 128 (Figure 12F) to minimize the operating current, and to allow very high-speed sensing of the differential latch amplifiers to pull nodes NA and NB towards Vcc and ground. When transistor 100 is on, the second terminal, such as the

drain terminal, of transistor 100 is at a high voltage. The second terminal of transistor 100 is coupled to a first terminal, such as the source terminal, of P-type transistors 95 and 98, thus resulting in a high voltage placed thereon. The gate of transistor 95 is coupled to the second terminal (such as the drain terminal) of transistor 98, while the gate of transistor 98 is coupled to the second terminal (such as the drain terminal) of transistor 95. Consequently, transistors 95 and 98 are turned on, and the second terminal of transistors 95 and 98 are charged to a high voltage or a logic-1 value (e.g., the supply voltage  $V_{cc}$  minus the threshold voltage  $V_{TP}$  of transistors 95 and 98). Note that, in one embodiment, transistor pairs 390 and 392 (Fig. 11F), 394 and 396 (Fig. 12F), and 95 and 98 (Fig. 13) are designed to have about the same threshold voltage  $V_{TP}$ , i.e., the same transistor width and length and have the same layout topology/orientation for each transistor pair. Nodes NA and NB are coupled to the second terminals of transistors 98 and 95, respectively, so that transistors 95, 98, and 100 pull up the voltage at nodes NA and NB from  $0.5V_{cc}$  to  $V_{cc}-V_{TP}$ . Nodes NA and NB are also coupled to the gates of transistors 95 and 98, respectively.

At power up, nodes NA and NB will be either at a low or high voltage. If both nodes are high, the leakage current of the P-N junctions of drains of transistors 92, 93, 95, and 98 will drain the voltage at nodes NA and NB to a steady state, which is  $V_{cc}-V_{TP}$ . If both nodes are low, transistors 95 and 98 will pull the voltage at nodes NA and NB up to  $V_{cc}-V_{TP}$ . If one of nodes NA or NB is either high or low, transistors 95 and

98 will pull the low voltage node to Vcc-VTP, and the high voltage node will be drained down to Vcc-VTP by the leakage current of the P-N junctions of drains of transistors 92, 93, 95, and 98. Therefore, after power  
5 up, both nodes NA and NB will be at Vcc-VTP before the receiver circuit starts to receive the incoming symbol during a data transfer cycle.

#### Timing Diagram for Multi-Symbol Receiver

10 Figure 14 is an exemplary timing diagram 150 for multi-symbol data transfer control for a multi-symbol receiver 48 in accordance with an embodiment of the present invention. The timing diagram illustrates the timing for a multi-symbol receiver 48 that receives an  
15 input signal SYMin and outputs decoded values D1 and D0.

The timing diagram includes exemplary waveforms for various signals including a symbol clock signal waveform 175, a clock (CLK) signal waveform 152, an  
20 enable (ENB) signal waveform 154, input signal SYMin waveform 156, multi-phase clock signal Ø1 waveform 158, Ø2 waveform 160, Ø3 waveform 162, Ø4 waveform 164, Øavg1 waveform 166, Øavg2 waveform 168, ØEN1 waveform 170, and ØEN2 waveform 172, and output values of data  
25 bits D1 and D0 waveform 174, all described in detail above. The symbol clock signal may be the same as a system clock signal. The CLK signal, which can be derived from the symbol clock signal, may be twice the frequency symbol clock signal. As such, the CLK signal  
30 may be considered to be a "half symbol" or "hsymbol" clock signal because its period is half that of the

symbol clock signal. The CLK signal is segmented into alternating odd and even-numbered clock cycles that, among other things, allows for a high clock and data rate, with each odd and even-numbered clock cycle

5 divided into two half-cycles of duration  $t_0$  and  $t_1$ . The ENB signal initiates the symbol transfer cycle when it drops to a low voltage level or logic-0 value. The input signal SYMin is received at the input of the multi-symbol receiver 48 and is shown with exemplary

10 voltage transitions for various symbol waveforms (i.e., symbol-10, symbol-11, symbol-01, symbol-00, etc.). For example, symbol-10 is shown which transitions from a voltage level  $V_{TT}$  at time period  $t_0$  to a voltage level  $V_L$  at time period  $t_1$  during an odd-numbered CLK cycle.

15 The phase signals  $\emptyset 1$  and  $\emptyset 2$  provide the timing during odd-numbered clock cycles while the phase signals  $\emptyset 3$  and  $\emptyset 4$  provide the timing during even-numbered clock cycles. Phase signal  $\emptyset 1$  is high during the transition from time period  $t_0$  (from a previous

20 even-numbered clock cycle) to time period  $t_0$  in odd-numbered clock cycles, while phase signal  $\emptyset 2$  is high during the transition from time period  $t_1$  (from a previous even-numbered clock cycle) to time period  $t_1$  in odd-numbered clock cycles. Similarly, for even-

25 numbered clock cycles, phase signal  $\emptyset 3$  is high during the transition from time period  $t_0$  (from a previous odd-numbered clock cycle) to time period  $t_0$ , and phase signal  $\emptyset 4$  is high during the transition from time period  $t_1$  (from a previous odd-numbered clock cycle) to

30 time period  $t_1$ . The frequency of each of phase signals

$\phi_1$ ,  $\phi_2$ ,  $\phi_3$ , and  $\phi_4$  is the same as the frequency of the symbol clock signal.

The phase signals  $\phi_{avg1}$  and  $\phi_{EN1}$  provide the timing during odd-numbered clock cycles, with phase signal  $\phi_{avg1}$  providing the timing for the averaging circuit 130 (Figure 12E) and phase signal  $\phi_{EN1}$  providing the timing for differential latch amplifier 126 (Figure 11F) and differential latch amplifier 128 (Figure 12F). The phase signals  $\phi_{avg2}$  and  $\phi_{EN2}$  provide the timing during even-numbered clock cycles, with phase signal  $\phi_{avg2}$  providing the timing for the averaging circuit 130 and phase signal  $\phi_{EN2}$  providing the timing for the differential latch amplifiers of the transition detector 370 and region detector 320. Phase signals  $\phi_{avg1}$  and  $\phi_{avg2}$  go high after respective phase signals  $\phi_2$  and  $\phi_4$  go low (at which time voltages have been stored in the capacitors) to initiate the averaging operation. Phase signals  $\phi_{avg1}$  and  $\phi_{avg2}$  remain high for a time sufficient to average the voltages stored in the capacitors. Phase signals  $\phi_{EN1}$  and  $\phi_{EN2}$  are low during pre-charging and equalization of nodes NA and NB, which occurs during the sampling operation of the differential signals Q+ and Q-. Phase signals  $\phi_{EN1}$  and  $\phi_{EN2}$  may then go high immediately after the averaging of Q- and Q+ and stay high while difference signals are amplified and held. At this time, the data bits D1 and D0 are available.

The waveforms illustrated in timing diagram 150 of Figure 14 are provided to facilitate an understanding of the timing control associated with the multi-symbol

receiver 48 and serves to summarize an exemplary timing control for processing the data, as described further herein.

The above-described embodiments of the present  
5 invention are merely meant to be illustrative and not limiting. It will thus be obvious to those skilled in the art that various changes and modifications may be made without departing from this invention in its broader aspects. Therefore, the appended claims  
10 encompass all such changes and modifications as fall within the true spirit and scope of this invention.